

## NAG Library Routine Document

### F07MHF (DSYRFS)

**Note:** before using this routine, please read the Users' Note for your implementation to check the interpretation of *bold italicised* terms and other implementation-dependent details.

#### 1 Purpose

F07MHF (DSYRFS) returns error bounds for the solution of a real symmetric indefinite system of linear equations with multiple right-hand sides,  $AX = B$ . It improves the solution by iterative refinement, in order to reduce the backward error as much as possible.

#### 2 Specification

```
SUBROUTINE F07MHF (UPLO, N, NRHS, A, LDA, AF, LDAF, IPIV, B, LDB, X, LDX,      &
                  FERR, BERR, WORK, IWORK, INFO)
INTEGER          N, NRHS, LDA, LDAF, IPIV(*), LDB, LDX, IWORK(N), INFO
REAL (KIND=nag_wp) A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*), FERR(NRHS),  &
                  BERR(NRHS), WORK(3*N)
CHARACTER(1)     UPLO
```

The routine may be called by its LAPACK name *dsyrfs*.

#### 3 Description

F07MHF (DSYRFS) returns the backward errors and estimated bounds on the forward errors for the solution of a real symmetric indefinite system of linear equations with multiple right-hand sides  $AX = B$ . The routine handles each right-hand side vector (stored as a column of the matrix  $B$ ) independently, so we describe the function of F07MHF (DSYRFS) in terms of a single right-hand side  $b$  and solution  $x$ .

Given a computed solution  $x$ , the routine computes the *component-wise backward error*  $\beta$ . This is the size of the smallest relative perturbation in each element of  $A$  and  $b$  such that  $x$  is the exact solution of a perturbed system

$$(A + \delta A)x = b + \delta b$$

$$|\delta a_{ij}| \leq \beta |a_{ij}| \quad \text{and} \quad |\delta b_i| \leq \beta |b_i|.$$

Then the routine estimates a bound for the *component-wise forward error* in the computed solution, defined by:

$$\max_i |x_i - \hat{x}_i| / \max_i |x_i|$$

where  $\hat{x}$  is the true solution.

For details of the method, see the F07 Chapter Introduction.

#### 4 References

Golub G H and Van Loan C F (1996) *Matrix Computations* (3rd Edition) Johns Hopkins University Press, Baltimore

## 5 Parameters

- 1: UPLO – CHARACTER(1) *Input*  
*On entry:* specifies whether the upper or lower triangular part of  $A$  is stored and how  $A$  is to be factorized.  
 UPLO = 'U'  
 The upper triangular part of  $A$  is stored and  $A$  is factorized as  $PUDU^T P^T$ , where  $U$  is upper triangular.  
 UPLO = 'L'  
 The lower triangular part of  $A$  is stored and  $A$  is factorized as  $PLDL^T P^T$ , where  $L$  is lower triangular.  
*Constraint:* UPLO = 'U' or 'L'.
- 2: N – INTEGER *Input*  
*On entry:*  $n$ , the order of the matrix  $A$ .  
*Constraint:*  $N \geq 0$ .
- 3: NRHS – INTEGER *Input*  
*On entry:*  $r$ , the number of right-hand sides.  
*Constraint:*  $NRHS \geq 0$ .
- 4: A(LDA,\*) – REAL (KIND=nag\_wp) array *Input*  
**Note:** the second dimension of the array  $A$  must be at least  $\max(1, N)$ .  
*On entry:* the  $n$  by  $n$  original symmetric matrix  $A$  as supplied to F07MDF (DSYTRF).
- 5: LDA – INTEGER *Input*  
*On entry:* the first dimension of the array  $A$  as declared in the (sub)program from which F07MHF (DSYRFS) is called.  
*Constraint:*  $LDA \geq \max(1, N)$ .
- 6: AF(LDAF,\*) – REAL (KIND=nag\_wp) array *Input*  
**Note:** the second dimension of the array  $AF$  must be at least  $\max(1, N)$ .  
*On entry:* details of the factorization of  $A$ , as returned by F07MDF (DSYTRF).
- 7: LDAF – INTEGER *Input*  
*On entry:* the first dimension of the array  $AF$  as declared in the (sub)program from which F07MHF (DSYRFS) is called.  
*Constraint:*  $LDAF \geq \max(1, N)$ .
- 8: IPIV(\*) – INTEGER array *Input*  
**Note:** the dimension of the array  $IPIV$  must be at least  $\max(1, N)$ .  
*On entry:* details of the interchanges and the block structure of  $D$ , as returned by F07MDF (DSYTRF).
- 9: B(LDB,\*) – REAL (KIND=nag\_wp) array *Input*  
**Note:** the second dimension of the array  $B$  must be at least  $\max(1, NRHS)$ .  
*On entry:* the  $n$  by  $r$  right-hand side matrix  $B$ .

- 10: LDB – INTEGER *Input*  
*On entry:* the first dimension of the array B as declared in the (sub)program from which F07MHF (DSYRFS) is called.  
*Constraint:*  $LDB \geq \max(1, N)$ .
- 11: X(LDX,\*) – REAL (KIND=nag\_wp) array *Input/Output*  
**Note:** the second dimension of the array X must be at least  $\max(1, NRHS)$ .  
*On entry:* the  $n$  by  $r$  solution matrix  $X$ , as returned by F07MEF (DSYTRS).  
*On exit:* the improved solution matrix  $X$ .
- 12: LDX – INTEGER *Input*  
*On entry:* the first dimension of the array X as declared in the (sub)program from which F07MHF (DSYRFS) is called.  
*Constraint:*  $LDX \geq \max(1, N)$ .
- 13: FERR(NRHS) – REAL (KIND=nag\_wp) array *Output*  
*On exit:*  $FERR(j)$  contains an estimated error bound for the  $j$ th solution vector, that is, the  $j$ th column of  $X$ , for  $j = 1, 2, \dots, r$ .
- 14: BERR(NRHS) – REAL (KIND=nag\_wp) array *Output*  
*On exit:*  $BERR(j)$  contains the component-wise backward error bound  $\beta$  for the  $j$ th solution vector, that is, the  $j$ th column of  $X$ , for  $j = 1, 2, \dots, r$ .
- 15: WORK( $3 \times N$ ) – REAL (KIND=nag\_wp) array *Workspace*
- 16: IWORK(N) – INTEGER array *Workspace*
- 17: INFO – INTEGER *Output*  
*On exit:*  $INFO = 0$  unless the routine detects an error (see Section 6).

## 6 Error Indicators and Warnings

Errors or warnings detected by the routine:

$INFO < 0$

If  $INFO = -i$ , the  $i$ th parameter had an illegal value. An explanatory message is output, and execution of the program is terminated.

## 7 Accuracy

The bounds returned in FERR are not rigorous, because they are estimated, not computed exactly; but in practice they almost always overestimate the actual error.

## 8 Further Comments

For each right-hand side, computation of the backward error involves a minimum of  $4n^2$  floating point operations. Each step of iterative refinement involves an additional  $6n^2$  operations. At most five steps of iterative refinement are performed, but usually only one or two steps are required.

Estimating the forward error involves solving a number of systems of linear equations of the form  $Ax = b$ ; the number is usually 4 or 5 and never more than 11. Each solution involves approximately  $2n^2$  operations.

The complex analogues of this routine are F07MVF (ZHERFS) for Hermitian matrices and F07NVF (ZSYRFS) for symmetric matrices.

## 9 Example

This example solves the system of equations  $AX = B$  using iterative refinement and to compute the forward and backward error bounds, where

$$A = \begin{pmatrix} 2.07 & 3.87 & 4.20 & -1.15 \\ 3.87 & -0.21 & 1.87 & 0.63 \\ 4.20 & 1.87 & 1.15 & 2.06 \\ -1.15 & 0.63 & 2.06 & -1.81 \end{pmatrix} \quad \text{and} \quad B = \begin{pmatrix} -9.50 & 27.85 \\ -8.38 & 9.90 \\ -6.07 & 19.25 \\ -0.96 & 3.93 \end{pmatrix}.$$

Here  $A$  is symmetric indefinite and must first be factorized by F07MDF (DSYTRF).

### 9.1 Program Text

```

Program f07mhfe

!      F07MHF Example Program Text

!      Mark 24 Release. NAG Copyright 2012.

!      .. Use Statements ..
Use nag_library, Only: dsyrfs, dsytrf, dsytrs, nag_wp, x04caf
!      .. Implicit None Statement ..
Implicit None
!      .. Parameters ..
Integer, Parameter          :: nin = 5, nout = 6
!      .. Local Scalars ..
Integer                     :: i, ifail, info, lda, ldaf, ldb, ldx, &
                             lwork, n, nrhs
Character (1)               :: uplo
!      .. Local Arrays ..
Real (Kind=nag_wp), Allocatable :: a(:,,:), af(:,,:), b(:,,:), berr(:), &
                             ferr(:), work(:), x(:,,:)
Integer, Allocatable        :: ipiv(:), iwork(:)
!      .. Executable Statements ..
Write (nout,*) 'F07MHF Example Program Results'
!      Skip heading in data file
Read (nin,*)
Read (nin,*) n, nrhs
lda = n
ldaf = n
ldb = n
ldx = n
lwork = 64*n
Allocate (a(lda,n),af(ldaf,n),b(ldb,nrhs),berr(nrhs),ferr(nrhs), &
          work(lwork),x(ldx,n),ipiv(n),iwork(n))

!      Read A and B from data file, and copy A to AF and B to X

Read (nin,*) uplo
If (uplo=='U') Then
  Do i = 1, n
    Read (nin,*) a(i,i:n)
    af(i,i:n) = a(i,i:n)
  End Do
Else If (uplo=='L') Then
  Do i = 1, n
    Read (nin,*) a(i,1:i)
    af(i,1:i) = a(i,1:i)
  End Do
End If
Read (nin,*)(b(i,1:nrhs),i=1,n)

x(1:n,1:nrhs) = b(1:n,1:nrhs)

```

```

!      Factorize A in the array AF
!      The NAG name equivalent of dsytrf is f07mdf
!      Call dsytrf(uplo,n,af,ldaf,ipiv,work,lwork,info)

      Write (nout,*)
      Flush (nout)
      If (info==0) Then

!      Compute solution in the array X
!      The NAG name equivalent of dsytrs is f07mef
!      Call dsytrs(uplo,n,nrhs,af,ldaf,ipiv,x,ldx,info)

!      Improve solution, and compute backward errors and
!      estimated bounds on the forward errors
!      The NAG name equivalent of dsyrfs is f07mhf
!      Call dsyrfs(uplo,n,nrhs,a,lda,af,ldaf,ipiv,b,ldb,x,ldx,ferr,berr,work, &
!      iwork,info)

!      Print solution

!      ifail: behaviour on error exit
!      =0 for hard exit, =1 for quiet-soft, =-1 for noisy-soft
!      ifail = 0
!      Call x04caf('General',' ',n,nrhs,x,ldx,'Solution(s)',ifail)

      Write (nout,*)
      Write (nout,*) 'Backward errors (machine-dependent)'
      Write (nout,99999) berr(1:nrhs)
      Write (nout,*) 'Estimated forward error bounds (machine-dependent)'
      Write (nout,99999) ferr(1:nrhs)
      Else
        Write (nout,*) 'The factor D is singular'
      End If

99999 Format ((3X,1P,7E11.1))
      End Program f07mhfe

```

## 9.2 Program Data

F07MHF Example Program Data

```

4 2          :Values of N and NRHS
'L'         :Value of UPLO
2.07
3.87 -0.21
4.20  1.87  1.15
-1.15  0.63  2.06 -1.81  :End of matrix A
-9.50  27.85
-8.38  9.90
-6.07  19.25
-0.96  3.93          :End of matrix B

```

## 9.3 Program Results

F07MHF Example Program Results

Solution(s)

	1	2
1	-4.0000	1.0000
2	-1.0000	4.0000
3	2.0000	3.0000
4	5.0000	2.0000

Backward errors (machine-dependent)

9.9E-17	8.3E-17
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Estimated forward error bounds (machine-dependent)

2.4E-14	3.2E-14
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