

## NAG Toolbox

### nag\_specfun\_fresnel\_s\_vector (s20aq)

#### 1 Purpose

nag\_specfun\_fresnel\_s\_vector (s20aq) returns an array of values for the Fresnel integral  $S(x)$ .

#### 2 Syntax

```
[f, ifail] = nag_specfun_fresnel_s_vector(x, 'n', n)
```

```
[f, ifail] = s20aq(x, 'n', n)
```

#### 3 Description

nag\_specfun\_fresnel\_s\_vector (s20aq) evaluates an approximation to the Fresnel integral

$$S(x_i) = \int_0^{x_i} \sin\left(\frac{\pi}{2}t^2\right) dt$$

for an array of arguments  $x_i$ , for  $i = 1, 2, \dots, n$ .

**Note:**  $S(x) = -S(-x)$ , so the approximation need only consider  $x \geq 0.0$ .

The function is based on three Chebyshev expansions:

For  $0 < x \leq 3$ ,

$$S(x) = x^3 \sum_{r=0} a_r T_r(t), \quad \text{with } t = 2\left(\frac{x}{3}\right)^4 - 1.$$

For  $x > 3$ ,

$$S(x) = \frac{1}{2} - \frac{f(x)}{x} \cos\left(\frac{\pi}{2}x^2\right) - \frac{g(x)}{x^3} \sin\left(\frac{\pi}{2}x^2\right),$$

where  $f(x) = \sum_{r=0} b_r T_r(t)$ ,

and  $g(x) = \sum_{r=0} c_r T_r(t)$ ,

with  $t = 2\left(\frac{3}{x}\right)^4 - 1$ .

For small  $x$ ,  $S(x) \simeq \frac{\pi}{6}x^3$ . This approximation is used when  $x$  is sufficiently small for the result to be correct to **machine precision**. For very small  $x$ , this approximation would underflow; the result is then set exactly to zero.

For large  $x$ ,  $f(x) \simeq \frac{1}{\pi}$  and  $g(x) \simeq \frac{1}{\pi^2}$ . Therefore for moderately large  $x$ , when  $\frac{1}{\pi^2 x^3}$  is negligible compared with  $\frac{1}{2}$ , the second term in the approximation for  $x > 3$  may be dropped. For very large  $x$ , when  $\frac{1}{\pi x}$  becomes negligible,  $S(x) \simeq \frac{1}{2}$ . However there will be considerable difficulties in calculating  $\cos\left(\frac{\pi}{2}x^2\right)$  accurately before this final limiting value can be used. Since  $\cos\left(\frac{\pi}{2}x^2\right)$  is periodic, its value is essentially determined by the fractional part of  $x^2$ . If  $x^2 = N + \theta$  where  $N$  is an integer and  $0 \leq \theta < 1$ , then  $\cos\left(\frac{\pi}{2}x^2\right)$  depends on  $\theta$  and on  $N$  modulo 4. By exploiting this fact, it is possible to

retain significance in the calculation of  $\cos\left(\frac{\pi}{2}x^2\right)$  either all the way to the very large  $x$  limit, or at least until the integer part of  $\frac{x}{2}$  is equal to the maximum integer allowed on the machine.

## 4 References

Abramowitz M and Stegun I A (1972) *Handbook of Mathematical Functions* (3rd Edition) Dover Publications

## 5 Parameters

### 5.1 Compulsory Input Parameters

1: **x(n)** – REAL (KIND=nag\_wp) array  
The argument  $x_i$  of the function, for  $i = 1, 2, \dots, \mathbf{n}$ .

### 5.2 Optional Input Parameters

1: **n** – INTEGER  
*Default:* the dimension of the array **x**.  
 $n$ , the number of points.  
*Constraint:*  $\mathbf{n} \geq 0$ .

### 5.3 Output Parameters

1: **f(n)** – REAL (KIND=nag\_wp) array  
 $S(x_i)$ , the function values.

2: **ifail** – INTEGER  
**ifail** = 0 unless the function detects an error (see Section 5).

## 6 Error Indicators and Warnings

Errors or warnings detected by the function:

**ifail** = 1 (*warning*)  
Constraint:  $\mathbf{n} \geq 0$ .

**ifail** = -99  
An unexpected error has been triggered by this routine. Please contact NAG.

**ifail** = -399  
Your licence key may have expired or may not have been installed correctly.

**ifail** = -999  
Dynamic memory allocation failed.

## 7 Accuracy

Let  $\delta$  and  $\epsilon$  be the relative errors in the argument and result respectively.

If  $\delta$  is somewhat larger than the *machine precision* (i.e., if  $\delta$  is due to data errors etc.), then  $\epsilon$  and  $\delta$  are approximately related by:

$$\epsilon \simeq \left| \frac{x \sin\left(\frac{\pi}{2}x^2\right)}{S(x)} \right| \delta.$$

Figure 1 shows the behaviour of the error amplification factor  $\left| \frac{x \sin\left(\frac{\pi}{2}x^2\right)}{S(x)} \right|$ .

However if  $\delta$  is of the same order as the *machine precision*, then rounding errors could make  $\epsilon$  slightly larger than the above relation predicts.

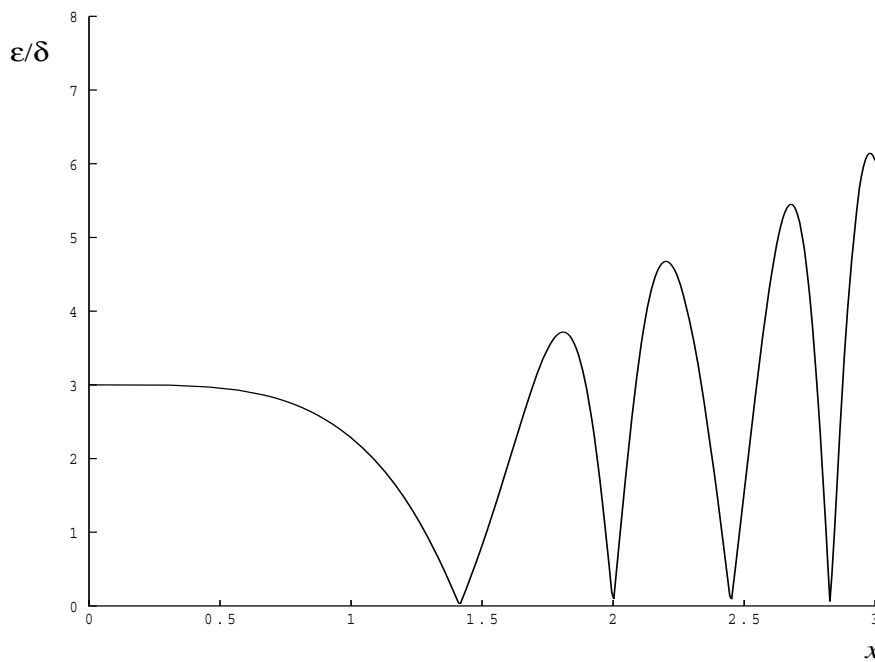
For small  $x$ ,  $\epsilon \simeq 3\delta$  and hence there is only moderate amplification of relative error. Of course for very small  $x$  where the correct result would underflow and exact zero is returned, relative error-control is lost.

For moderately large values of  $x$ ,

$$\epsilon \simeq \left| 2x \sin\left(\frac{\pi}{2}x^2\right) \right| \delta$$

and the result will be subject to increasingly large amplification of errors. However the above relation breaks down for large values of  $x$  (i.e., when  $\frac{1}{x^2}$  is of the order of the *machine precision*); in this region the relative error in the result is essentially bounded by  $\frac{2}{\pi x}$ .

Hence the effects of error amplification are limited and at worst the relative error loss should not exceed half the possible number of significant figures.



**Figure 1**

## **8 Further Comments**

None.

## 9 Example

This example reads values of  $\mathbf{x}$  from a file, evaluates the function at each value of  $x_i$  and prints the results.

### 9.1 Program Text

```
function s20aq_example
fprintf('s20aq example results\n\n');
x = [0; 0.5; 1; 2; 4; 5; 6; 8; 10; -1; 1000];
[f, ifail] = s20aq(x);
fprintf('      x          S(x)\n');
for i=1:numel(x)
    fprintf('%12.3e%12.3e\n', x(i), f(i));
end
```

### 9.2 Program Results

```
s20aq example results

      x          S(x)
0.000e+00    0.000e+00
5.000e-01    6.473e-02
1.000e+00    4.383e-01
2.000e+00    3.434e-01
4.000e+00    4.205e-01
5.000e+00    4.992e-01
6.000e+00    4.470e-01
8.000e+00    4.602e-01
1.000e+01    4.682e-01
-1.000e+00   -4.383e-01
1.000e+03    4.997e-01
```

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