

## NAG Toolbox

### nag\_lapack\_zhprfs (f07pv)

#### 1 Purpose

nag\_lapack\_zhprfs (f07pv) returns error bounds for the solution of a complex Hermitian indefinite system of linear equations with multiple right-hand sides,  $AX = B$ , using packed storage. It improves the solution by iterative refinement, in order to reduce the backward error as much as possible.

#### 2 Syntax

```
[x, ferr, berr, info] = nag_lapack_zhprfs(uplo, ap, afp, ipiv, b, x, 'n', n,
'nrhs_p', nrhs_p)
[x, ferr, berr, info] = f07pv(uplo, ap, afp, ipiv, b, x, 'n', n, 'nrhs_p',
nrhs_p)
```

#### 3 Description

nag\_lapack\_zhprfs (f07pv) returns the backward errors and estimated bounds on the forward errors for the solution of a complex Hermitian indefinite system of linear equations with multiple right-hand sides  $AX = B$ , using packed storage. The function handles each right-hand side vector (stored as a column of the matrix  $B$ ) independently, so we describe the function of nag\_lapack\_zhprfs (f07pv) in terms of a single right-hand side  $b$  and solution  $x$ .

Given a computed solution  $x$ , the function computes the *component-wise backward error*  $\beta$ . This is the size of the smallest relative perturbation in each element of  $A$  and  $b$  such that  $x$  is the exact solution of a perturbed system

$$(A + \delta A)x = b + \delta b$$

$$|\delta a_{ij}| \leq \beta |a_{ij}| \quad \text{and} \quad |\delta b_i| \leq \beta |b_i|.$$

Then the function estimates a bound for the *component-wise forward error* in the computed solution, defined by:

$$\max_i |x_i - \hat{x}_i| / \max_i |x_i|$$

where  $\hat{x}$  is the true solution.

For details of the method, see the F07 Chapter Introduction.

#### 4 References

Golub G H and Van Loan C F (1996) *Matrix Computations* (3rd Edition) Johns Hopkins University Press, Baltimore

#### 5 Parameters

##### 5.1 Compulsory Input Parameters

1: **uplo** – CHARACTER(1)

Specifies whether the upper or lower triangular part of  $A$  is stored and how  $A$  is to be factorized.

**uplo** = 'U'

The upper triangular part of  $A$  is stored and  $A$  is factorized as  $PUDU^H P^T$ , where  $U$  is upper triangular.

**uplo** = 'L'

The lower triangular part of  $A$  is stored and  $A$  is factorized as  $PLDL^H P^T$ , where  $L$  is lower triangular.

*Constraint:* **uplo** = 'U' or 'L'.

2: **ap**(:) – COMPLEX (KIND=nag\_wp) array

The dimension of the array **ap** must be at least  $\max(1, n \times (n + 1)/2)$

The  $n$  by  $n$  original Hermitian matrix  $A$  as supplied to nag\_lapack\_zhptrf (f07pr).

3: **afp**(:) – COMPLEX (KIND=nag\_wp) array

The dimension of the array **afp** must be at least  $\max(1, n \times (n + 1)/2)$

The factorization of  $A$  stored in packed form, as returned by nag\_lapack\_zhptrf (f07pr).

4: **ipiv**(:) – INTEGER array

The dimension of the array **ipiv** must be at least  $\max(1, n)$

Details of the interchanges and the block structure of  $D$ , as returned by nag\_lapack\_zhptrf (f07pr).

5: **b**(ldb,:) – COMPLEX (KIND=nag\_wp) array

The first dimension of the array **b** must be at least  $\max(1, n)$ .

The second dimension of the array **b** must be at least  $\max(1, nrhs\_p)$ .

The  $n$  by  $r$  right-hand side matrix  $B$ .

6: **x**(ldx,:) – COMPLEX (KIND=nag\_wp) array

The first dimension of the array **x** must be at least  $\max(1, n)$ .

The second dimension of the array **x** must be at least  $\max(1, nrhs\_p)$ .

The  $n$  by  $r$  solution matrix  $X$ , as returned by nag\_lapack\_zhptrs (f07ps).

## 5.2 Optional Input Parameters

1: **n** – INTEGER

*Default:* the first dimension of the arrays **b**, **x** and the dimension of the array **ipiv**.

$n$ , the order of the matrix  $A$ .

*Constraint:*  $n \geq 0$ .

2: **nrhs\_p** – INTEGER

*Default:* the second dimension of the arrays **b**, **x**. (An error is raised if these dimensions are not equal.)

$r$ , the number of right-hand sides.

*Constraint:*  $nrhs\_p \geq 0$ .

## 5.3 Output Parameters

1: **x**(ldx,:) – COMPLEX (KIND=nag\_wp) array

The first dimension of the array **x** will be  $\max(1, n)$ .

The second dimension of the array **x** will be  $\max(1, nrhs\_p)$ .

The improved solution matrix  $X$ .

- 2: **ferr**(nrhs\_p) – REAL (KIND=nag\_wp) array  
**ferr**(*j*) contains an estimated error bound for the *j*th solution vector, that is, the *j*th column of *X*, for  $j = 1, 2, \dots, r$ .
- 3: **berr**(nrhs\_p) – REAL (KIND=nag\_wp) array  
**berr**(*j*) contains the component-wise backward error bound  $\beta$  for the *j*th solution vector, that is, the *j*th column of *X*, for  $j = 1, 2, \dots, r$ .
- 4: **info** – INTEGER  
**info** = 0 unless the function detects an error (see Section 6).

## 6 Error Indicators and Warnings

**info** < 0

If **info** =  $-i$ , argument *i* had an illegal value. An explanatory message is output, and execution of the program is terminated.

## 7 Accuracy

The bounds returned in **ferr** are not rigorous, because they are estimated, not computed exactly; but in practice they almost always overestimate the actual error.

## 8 Further Comments

For each right-hand side, computation of the backward error involves a minimum of  $16n^2$  real floating-point operations. Each step of iterative refinement involves an additional  $24n^2$  real operations. At most five steps of iterative refinement are performed, but usually only 1 or 2 steps are required.

Estimating the forward error involves solving a number of systems of linear equations of the form  $Ax = b$ ; the number is usually 5 and never more than 11. Each solution involves approximately  $8n^2$  real operations.

The real analogue of this function is nag\_lapack\_dsprfs (f07ph).

## 9 Example

This example solves the system of equations  $AX = B$  using iterative refinement and to compute the forward and backward error bounds, where

$$A = \begin{pmatrix} -1.36 + 0.00i & 1.58 + 0.90i & 2.21 - 0.21i & 3.91 + 1.50i \\ 1.58 - 0.90i & -8.87 + 0.00i & -1.84 - 0.03i & -1.78 + 1.18i \\ 2.21 + 0.21i & -1.84 + 0.03i & -4.63 + 0.00i & 0.11 + 0.11i \\ 3.91 - 1.50i & -1.78 - 1.18i & 0.11 - 0.11i & -1.84 + 0.00i \end{pmatrix}$$

and

$$B = \begin{pmatrix} 7.79 + 5.48i & -35.39 + 18.01i \\ -0.77 - 16.05i & 4.23 - 70.02i \\ -9.58 + 3.88i & -24.79 - 8.40i \\ 2.98 - 10.18i & 28.68 - 39.89i \end{pmatrix}.$$

Here *A* is Hermitian indefinite, stored in packed form, and must first be factorized by nag\_lapack\_zhptrf (f07pr).

## 9.1 Program Text

```
function f07pv_example

fprintf('f07pv example results\n\n');

% Hermitian indefinite matrix A (Lower triangular part stored in packed form)
uplo = 'L';
n = nag_int(4);
ap = [-1.36 + 0i; 1.58 - 0.9i; 2.21 + 0.21i; 3.91 - 1.5i;
      -8.87 + 0i; -1.84 + 0.03i; -1.78 - 1.18i;
      -4.63 + 0i; 0.11 - 0.11i;
      -1.84 + 0i];

% Factorize
[apf, ipiv, info] = f07pr( ...
                        uplo, n, ap);

% RHS
b = [ 7.79 + 5.48i, -35.39 + 18.01i;
     -0.77 - 16.05i, 4.23 - 70.02i;
     -9.58 + 3.88i, -24.79 - 8.40i;
     2.98 - 10.18i, 28.68 - 39.89i];

% Solve
[x, info] = f07ps( ...
               uplo, apf, ipiv, b);

% Refine
[x, ferr, berr, info] = f07pv( ...
                            uplo, ap, apf, ipiv, b, x);

disp('Solution(s)');
disp(x);
fprintf('Backward errors (machine-dependent)\n  ')
fprintf('%11.1e', berr);
fprintf('\nEstimated forward error bounds (machine-dependent)\n  ')
fprintf('%11.1e', ferr);
fprintf('\n');
```

## 9.2 Program Results

```
f07pv example results

Solution(s)
 1.0000 - 1.0000i   3.0000 - 4.0000i
-1.0000 + 2.0000i  -1.0000 + 5.0000i
 3.0000 - 2.0000i   7.0000 - 2.0000i
 2.0000 + 1.0000i  -8.0000 + 6.0000i

Backward errors (machine-dependent)
 5.6e-17   8.1e-17

Estimated forward error bounds (machine-dependent)
 2.5e-15   3.0e-15
```

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