

NAG Toolbox

nag_lapack_dgerfs (f07ah)

1 Purpose

nag_lapack_dgerfs (f07ah) returns error bounds for the solution of a real system of linear equations with multiple right-hand sides, $AX = B$ or $A^T X = B$. It improves the solution by iterative refinement, in order to reduce the backward error as much as possible.

2 Syntax

```
[x, ferr, berr, info] = nag_lapack_dgerfs(trans, a, af, ipiv, b, x, 'n', n,
'nrhs_p', nrhs_p)
```

```
[x, ferr, berr, info] = f07ah(trans, a, af, ipiv, b, x, 'n', n, 'nrhs_p', nrhs_p)
```

3 Description

nag_lapack_dgerfs (f07ah) returns the backward errors and estimated bounds on the forward errors for the solution of a real system of linear equations with multiple right-hand sides $AX = B$ or $A^T X = B$. The function handles each right-hand side vector (stored as a column of the matrix B) independently, so we describe the function of nag_lapack_dgerfs (f07ah) in terms of a single right-hand side b and solution x .

Given a computed solution x , the function computes the *component-wise backward error* β . This is the size of the smallest relative perturbation in each element of A and b such that x is the exact solution of a perturbed system

$$(A + \delta A)x = b + \delta b$$

$$|\delta a_{ij}| \leq \beta |a_{ij}| \quad \text{and} \quad |\delta b_i| \leq \beta |b_i|.$$

Then the function estimates a bound for the *component-wise forward error* in the computed solution, defined by:

$$\max_i |x_i - \hat{x}_i| / \max_i |x_i|$$

where \hat{x} is the true solution.

For details of the method, see the F07 Chapter Introduction.

4 References

Golub G H and Van Loan C F (1996) *Matrix Computations* (3rd Edition) Johns Hopkins University Press, Baltimore

5 Parameters

5.1 Compulsory Input Parameters

1: **trans** – CHARACTER(1)

Indicates the form of the linear equations for which X is the computed solution.

trans = 'N'

The linear equations are of the form $AX = B$.

trans = 'T' or 'C'

The linear equations are of the form $A^T X = B$.

Constraint: **trans** = 'N', 'T' or 'C'.

2: **a**(*lda*,:) – REAL (KIND=nag_wp) array

The first dimension of the array **a** must be at least $\max(1, \mathbf{n})$.

The second dimension of the array **a** must be at least $\max(1, \mathbf{n})$.

The n by n original matrix A as supplied to nag_lapack_dgetrf (f07ad).

3: **af**(*ldaf*,:) – REAL (KIND=nag_wp) array

The first dimension of the array **af** must be at least $\max(1, \mathbf{n})$.

The second dimension of the array **af** must be at least $\max(1, \mathbf{n})$.

The LU factorization of A , as returned by nag_lapack_dgetrf (f07ad).

4: **ipiv**(:) – INTEGER array

The dimension of the array **ipiv** must be at least $\max(1, \mathbf{n})$

The pivot indices, as returned by nag_lapack_dgetrf (f07ad).

5: **b**(*ldb*,:) – REAL (KIND=nag_wp) array

The first dimension of the array **b** must be at least $\max(1, \mathbf{n})$.

The second dimension of the array **b** must be at least $\max(1, \mathbf{nrhs_p})$.

The n by r right-hand side matrix B .

6: **x**(*ldx*,:) – REAL (KIND=nag_wp) array

The first dimension of the array **x** must be at least $\max(1, \mathbf{n})$.

The second dimension of the array **x** must be at least $\max(1, \mathbf{nrhs_p})$.

The n by r solution matrix X , as returned by nag_lapack_dgetrs (f07ae).

5.2 Optional Input Parameters

1: **n** – INTEGER

Default: the first dimension of the arrays **a**, **af**, **b**, **x** and the second dimension of the arrays **a**, **af**, **ipiv**.

n , the order of the matrix A .

Constraint: $\mathbf{n} \geq 0$.

2: **nrhs_p** – INTEGER

Default: the second dimension of the arrays **b**, **x**. (An error is raised if these dimensions are not equal.)

r , the number of right-hand sides.

Constraint: $\mathbf{nrhs_p} \geq 0$.

5.3 Output Parameters

1: **x**(*ldx*,:) – REAL (KIND=nag_wp) array

The first dimension of the array **x** will be $\max(1, \mathbf{n})$.

The second dimension of the array \mathbf{x} will be $\max(1, \mathbf{nrhs_p})$.

The improved solution matrix X .

2: **ferr(nrhs_p)** – REAL (KIND=nag_wp) array

ferr(j) contains an estimated error bound for the j th solution vector, that is, the j th column of X , for $j = 1, 2, \dots, r$.

3: **berr(nrhs_p)** – REAL (KIND=nag_wp) array

berr(j) contains the component-wise backward error bound β for the j th solution vector, that is, the j th column of X , for $j = 1, 2, \dots, r$.

4: **info** – INTEGER

info = 0 unless the function detects an error (see Section 6).

6 Error Indicators and Warnings

info < 0

If **info** = $-i$, argument i had an illegal value. An explanatory message is output, and execution of the program is terminated.

7 Accuracy

The bounds returned in **ferr** are not rigorous, because they are estimated, not computed exactly; but in practice they almost always overestimate the actual error.

8 Further Comments

For each right-hand side, computation of the backward error involves a minimum of $4n^2$ floating-point operations. Each step of iterative refinement involves an additional $6n^2$ operations. At most five steps of iterative refinement are performed, but usually only one or two steps are required.

Estimating the forward error involves solving a number of systems of linear equations of the form $Ax = b$ or $A^T x = b$; the number is usually 4 or 5 and never more than 11. Each solution involves approximately $2n^2$ operations.

The complex analogue of this function is `nag_lapack_zgerfs` (f07av).

9 Example

This example solves the system of equations $AX = B$ using iterative refinement and to compute the forward and backward error bounds, where

$$A = \begin{pmatrix} 1.80 & 2.88 & 2.05 & -0.89 \\ 5.25 & -2.95 & -0.95 & -3.80 \\ 1.58 & -2.69 & -2.90 & -1.04 \\ -1.11 & -0.66 & -0.59 & 0.80 \end{pmatrix} \quad \text{and} \quad B = \begin{pmatrix} 9.52 & 18.47 \\ 24.35 & 2.25 \\ 0.77 & -13.28 \\ -6.22 & -6.21 \end{pmatrix}.$$

Here A is nonsymmetric and must first be factorized by `nag_lapack_dgetrf` (f07ad).

9.1 Program Text

```
function f07ah_example

fprintf('f07ah example results\n\n');

a = [ 1.80,  2.88,  2.05, -0.89;
      5.25, -2.95, -0.95, -3.80;
      1.58, -2.69, -2.90, -1.04;
      -1.11, -0.66, -0.59,  0.80];
b = [ 9.52, 18.47;
      24.35,  2.25;
      0.77,-13.28;
      -6.22, -6.21];

% Factorize a
[af, ipiv, info] = f07ad(a);

% Compute solution x
trans = 'N';
[x, ferr, berr, info] = f07ah( ...
                             trans, a, af, ipiv, b, b);

[ifail] = x04ca( ...
               'General', ' ', x, 'Solution(s)');

fprintf('\nBackward errors (machine-dependent)\n  ')
fprintf('%11.1e', berr);
fprintf('\nEstimated forward error bounds (machine-dependent)\n  ')
fprintf('%11.1e', ferr);
fprintf('\n');
```

9.2 Program Results

```
f07ah example results

Solution(s)
      1      2
1      1.0000      3.0000
2     -1.0000      2.0000
3      3.0000      4.0000
4     -5.0000      1.0000

Backward errors (machine-dependent)
      6.5e-17      8.9e-17
Estimated forward error bounds (machine-dependent)
      2.5e-14      3.5e-14
```
