

## NAG Toolbox

### nag\_eigen\_real\_gen\_partialsvd (f02wg)

#### 1 Purpose

nag\_eigen\_real\_gen\_partialsvd (f02wg) returns leading terms in the singular value decomposition (SVD) of a real general matrix and computes the corresponding left and right singular vectors.

#### 2 Syntax

```
[nconv, sigma, u, v, resid, user, ifail] = nag_eigen_real_gen_partialsvd(m, n,
k, ncv, av, 'user', user)
[nconv, sigma, u, v, resid, user, ifail] = f02wg(m, n, k, ncv, av, 'user', user)
```

#### 3 Description

nag\_eigen\_real\_gen\_partialsvd (f02wg) computes a few,  $k$ , of the largest singular values and corresponding vectors of an  $m$  by  $n$  matrix  $A$ . The value of  $k$  should be small relative to  $m$  and  $n$ , for example  $k \sim O(\min(m, n))$ . The full singular value decomposition (SVD) of an  $m$  by  $n$  matrix  $A$  is given by

$$A = U\Sigma V^T,$$

where  $U$  and  $V$  are orthogonal and  $\Sigma$  is an  $m$  by  $n$  diagonal matrix with real diagonal elements,  $\sigma_i$ , such that

$$\sigma_1 \geq \sigma_2 \geq \dots \geq \sigma_{\min(m, n)} \geq 0.$$

The  $\sigma_i$  are the *singular values* of  $A$  and the first  $\min(m, n)$  columns of  $U$  and  $V$  are the *left* and *right singular vectors* of  $A$ .

If  $U_k, V_k$  denote the leading  $k$  columns of  $U$  and  $V$  respectively, and if  $\Sigma_k$  denotes the leading principal submatrix of  $\Sigma$ , then

$$A_k \equiv U_k \Sigma_k V_k^T$$

is the best rank- $k$  approximation to  $A$  in both the 2-norm and the Frobenius norm.

The singular values and singular vectors satisfy

$$Av_i = \sigma_i u_i \quad \text{and} \quad A^T u_i = \sigma_i v_i \quad \text{so that} \quad A^T A v_i = \sigma_i^2 v_i \quad \text{and} \quad A A^T u_i = \sigma_i^2 u_i,$$

where  $u_i$  and  $v_i$  are the  $i$ th columns of  $U_k$  and  $V_k$  respectively.

Thus, for  $m \geq n$ , the largest singular values and corresponding right singular vectors are computed by finding eigenvalues and eigenvectors for the symmetric matrix  $A^T A$ . For  $m < n$ , the largest singular values and corresponding left singular vectors are computed by finding eigenvalues and eigenvectors for the symmetric matrix  $A A^T$ . These eigenvalues and eigenvectors are found using functions from Chapter F12. You should read the F12 Chapter Introduction for full details of the method used here.

The real matrix  $A$  is not explicitly supplied to nag\_eigen\_real\_gen\_partialsvd (f02wg). Instead, you are required to supply a function, **av**, that must calculate one of the requested matrix-vector products  $Ax$  or  $A^T x$  for a given real vector  $x$  (of length  $n$  or  $m$  respectively).

#### 4 References

Wilkinson J H (1978) Singular Value Decomposition – Basic Aspects *Numerical Software – Needs and Availability* (ed D A H Jacobs) Academic Press

## 5 Parameters

### 5.1 Compulsory Input Parameters

1: **m** – INTEGER

$m$ , the number of rows of the matrix  $A$ .

*Constraint:*  $\mathbf{m} \geq 0$ .

If  $\mathbf{m} = 0$ , an immediate return is effected.

2: **n** – INTEGER

$n$ , the number of columns of the matrix  $A$ .

*Constraint:*  $\mathbf{n} \geq 0$ .

If  $\mathbf{n} = 0$ , an immediate return is effected.

3: **k** – INTEGER

$k$ , the number of singular values to be computed.

*Constraint:*  $0 < \mathbf{k} < \min(\mathbf{m}, \mathbf{n}) - 1$ .

4: **ncv** – INTEGER

The dimension of the arrays **sigma** and **resid** and the second dimension of the arrays **u** and **v**. this is the number of Lanczos basis vectors to use during the computation of the largest eigenvalues of  $A^T A$  ( $m \geq n$ ) or  $AA^T$  ( $m < n$ ).

At present there is no *a priori* analysis to guide the selection of **ncv** relative to **k**. However, it is recommended that  $\mathbf{ncv} \geq 2 \times \mathbf{k} + 1$ . If many problems of the same type are to be solved, you should experiment with varying **ncv** while keeping **k** fixed for a given test problem. This will usually decrease the required number of matrix-vector operations but it also increases the internal storage required to maintain the orthogonal basis vectors. The optimal ‘cross-over’ with respect to CPU time is problem dependent and must be determined empirically.

*Constraint:*  $\mathbf{k} < \mathbf{ncv} \leq \min(\mathbf{m}, \mathbf{n})$ .

5: **av** – SUBROUTINE, supplied by the user.

**av** must return the vector result of the matrix-vector product  $Ax$  or  $A^T x$ , as indicated by the input value of **iflag**, for the given vector  $x$ .

**av** is called from `nag_eigen_real_gen_partialsvd (f02wg)` with the argument as supplied to `nag_eigen_real_gen_partialsvd (f02wg)`. You are free to use these arrays to supply information to **av**.

```
[iflag, ax, user] = av(iflag, m, n, x, user)
```

#### Input Parameters

1: **iflag** – INTEGER

If **iflag** = 1, **ax** must return the  $m$ -vector result of the matrix-vector product  $Ax$ .

If **iflag** = 2, **ax** must return the  $n$ -vector result of the matrix-vector product  $A^T x$ .

2: **m** – INTEGER

The number of rows of the matrix  $A$ .

3:	<b>n</b> – INTEGER
	The number of columns of the matrix $A$ .
4:	<b>x</b> (:) – REAL (KIND=nag_wp) array
	The vector to be pre-multiplied by the matrix $A$ or $A^T$ .
5:	<b>user</b> – INTEGER array
	<b>av</b> is called from nag_eigen_real_gen_partialsvd (f02wg) with the object supplied to nag_eigen_real_gen_partialsvd (f02wg).
<b>Output Parameters</b>	
1:	<b>iflag</b> – INTEGER
	May be used as a flag to indicate a failure in the computation of $Ax$ or $A^T x$ . If <b>iflag</b> is negative on exit from <b>av</b> , nag_eigen_real_gen_partialsvd (f02wg) will exit immediately with <b>ifail</b> set to <b>iflag</b> .
2:	<b>ax</b> (:) – REAL (KIND=nag_wp) array
	If <b>iflag</b> = 1, contains the $m$ -vector result of the matrix-vector product $Ax$ .
	If <b>iflag</b> = 2, contains the $n$ -vector result of the matrix-vector product $A^T x$ .
3:	<b>user</b> – INTEGER array

## 5.2 Optional Input Parameters

1: **user** – INTEGER array

**user** is not used by nag\_eigen\_real\_gen\_partialsvd (f02wg), but is passed to **av**. Note that for large objects it may be more efficient to use a global variable which is accessible from the m-files than to use **user**.

## 5.3 Output Parameters

1: **nconv** – INTEGER

The number of converged singular values found.

2: **sigma**(nconv) – REAL (KIND=nag\_wp) array

The **nconv** converged singular values are stored in the first **nconv** elements of **sigma**.

3: **u**(ldu, nconv) – REAL (KIND=nag\_wp) array

The left singular vectors corresponding to the singular values stored in **sigma**.

The  $i$ th element of the  $j$ th left singular vector  $u_j$  is stored in **u**( $i, j$ ), for  $i = 1, 2, \dots, m$  and  $j = 1, 2, \dots, \mathbf{nconv}$ .

4: **v**(ldv, nconv) – REAL (KIND=nag\_wp) array

The right singular vectors corresponding to the singular values stored in **sigma**.

The  $i$ th element of the  $j$ th right singular vector  $v_j$  is stored in **v**( $i, j$ ), for  $i = 1, 2, \dots, n$  and  $j = 1, 2, \dots, \mathbf{nconv}$ .

5: **resid(ncv)** – REAL (KIND=nag\_wp) array

The residual  $\|Av_j - \sigma_j u_j\|$ , for  $m \geq n$ , or  $\|A^T u_j - \sigma_j v_j\|$ , for  $m < n$ , for each of the converged singular values  $\sigma_j$  and corresponding left and right singular vectors  $u_j$  and  $v_j$ .

6: **user** – INTEGER array

7: **ifail** – INTEGER

**ifail** = 0 unless the function detects an error (see Section 5).

nag\_eigen\_real\_gen\_partialsvd (f02wg) returns with **ifail** = 0 if at least  $k$  singular values have converged and the corresponding left and right singular vectors have been computed.

## 6 Error Indicators and Warnings

Errors or warnings detected by the function:

**ifail** = 1

Constraint:  $\mathbf{m} \geq 0$ .

**ifail** = 2

Constraint:  $\mathbf{n} \geq 0$ .

**ifail** = 3

Constraint:  $\mathbf{k} > 0$ .

**ifail** = 4

Constraint:  $\mathbf{k} < \mathbf{ncv} \leq \min(\mathbf{m}, \mathbf{n})$ .

**ifail** = 5

Constraint:  $ldu \geq \mathbf{m}$ .

**ifail** = 6

Constraint:  $ldv \geq \mathbf{n}$ .

**ifail** = 8

The maximum number of iterations has been reached.

**ifail** = 9

No shifts could be applied during a cycle of the implicitly restarted Lanczos iteration.

**ifail** = 10

Could not build a full Lanczos factorization.

**ifail** = 11

The number of eigenvalues found to sufficient accuracy is zero.

**ifail** = 20

An error occurred during an internal call. Consider increasing the size of **ncv** relative to **k**.

**ifail** < 0

On output from user-defined function **av**, **iflag** was set to a negative value, .

**ifail** = -99

An unexpected error has been triggered by this routine. Please contact NAG.

**ifail** = -399

Your licence key may have expired or may not have been installed correctly.

**ifail** = -999

Dynamic memory allocation failed.

## 7 Accuracy

See Section 2.14.2 in the F08 Chapter Introduction.

## 8 Further Comments

None.

## 9 Example

This example finds the four largest singular values ( $\sigma$ ) and corresponding right and left singular vectors for the matrix  $A$ , where  $A$  is the  $m$  by  $n$  real matrix derived from the simplest finite difference discretization of the two-dimensional kernel  $k(s,t)dt$  where

$$k(s,t) = \begin{cases} s(t-1) & \text{if } 0 \leq s \leq t \leq 1 \\ t(s-1) & \text{if } 0 \leq t < s \leq 1 \end{cases}$$

### 9.1 Program Text

```
function f02wg_example

fprintf('f02wg example results\n\n');

m = nag_int(100);
n = nag_int(500);
k = nag_int(4);
ncv = nag_int(10);

[nconv, sigma, u, v, resid, user, ifail] = ...
f02wg(m, n, k, ncv, @av);

res = [sigma(1:nconv) resid(1:nconv)];
fprintf(' Singular Value Residual\n');
fprintf(' %10.5f %12.2e\n', res');

function [iflag, ax, user] = av(iflag, m, n, x, user)
    if (iflag == 1)
        ax = zeros(m, 1);
    else
        ax = zeros(n, 1);
    end

    % Computes w <- A*x or w <- Trans(A)*x.
    h = 1/(double(m)+1);
    k = 1/(double(n)+1);
    if (iflag == 1)
        t = 0;
        for j = 1:n
            t = t + k;
            s = 0;
            ktx = k*(t-1)*x(j);
            for i = 1:min(j,m)
                s = s + h;
                ax(i) = ax(i) + ktx*s;
            end
        end
    end
end
```

```
end
ktx = k*t*x(j);
for i = j+1:m
    s = s + h;
    ax(i) = ax(i) + ktx*(s-1);
end
end
else
    t = 0;
    for j = 1:n
        t = t + k;
        s = 0;
        for i = 1:min(j,m)
            s = s + h;
            ax(j) = ax(j) + k*s*(t-1)*x(i);
        end
        for i = j+1:m
            s = s + h;
            ax(j) = ax(j) + k*t*(s-1)*x(i);
        end
    end
end
end
```

## 9.2 Program Results

f02wg example results

Singular Value	Residual
0.00830	1.82e-18
0.01223	3.95e-18
0.02381	1.95e-17
0.11274	2.53e-17

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