NAG Library Function Document

nag_superlu_solve_lu (f11mfc)

1 Purpose

nag_superlu_solve_lu (f11mfc) solves a real sparse system of linear equations with multiple right-hand sides given an \( LU \) factorization of the sparse matrix computed by nag_superlu_lu_factorize (f11mec).

2 Specification

```c
#include <nag.h>
#include <nagf11.h>
void nag_superlu_solve_lu (Nag_OrderType order, Nag_TransType trans,
    Integer n, const Integer iprm[], const Integer il[],
    const double lval[], const Integer iu[], const double uval[],
    Integer nrhs, double b[], Integer pdb, NagError *fail)
```

3 Description

nag_superlu_solve_lu (f11mfc) solves a real system of linear equations with multiple right-hand sides \( AX = B \) or \( A^T X = B \) according to the value of the argument `trans`, where the matrix factorization \( P_rAP_c = LU \) corresponds to an \( LU \) decomposition of a sparse matrix stored in compressed column (Harwell–Boeing) format, as computed by nag_superlu_lu_factorize (f11mec).

In the above decomposition \( L \) is a lower triangular sparse matrix with unit diagonal elements and \( U \) is an upper triangular sparse matrix; \( P_r \) and \( P_c \) are permutation matrices.

4 References

None.

5 Arguments

1: `order` – Nag_OrderType

   Input

   `On entry:` the `order` argument specifies the two-dimensional storage scheme being used, i.e., row-major ordering or column-major ordering. C language defined storage is specified by `order = Nag_RowMajor`. See Section 3.2.1.3 in the Essential Introduction for a more detailed explanation of the use of this argument.

   Constraint: `order = Nag_RowMajor` or `Nag_ColMajor`.

2: `trans` – Nag_TransType

   Input

   `On entry:` specifies whether \( AX = B \) or \( A^T X = B \) is solved.

   trans = Nag_NoTrans
   \( AX = B \) is solved.

   trans = Nag_Trans
   \( A^T X = B \) is solved.

   Constraint: `trans = Nag_NoTrans` or `Nag_Trans`. 
3: \( \text{n} \) – Integer \( \quad \) \text{Input}

\text{On entry: } n, \text{ the order of the matrix } A.

\text{Constraint: } n \geq 0.

4: \( \text{iprm}[7 \times n] \) – const Integer \( \quad \) \text{Input}

\text{On entry: } \text{the column permutation which defines } P_c, \text{ the row permutation which defines } P_r, \text{ plus associated data structures as computed by } \text{nag}\_\text{superlu}\_\text{lu}\_\text{factorize} (f11mec).

5: \( \text{il}[\text{dim}] \) – const Integer \( \quad \) \text{Input}

\text{Note: } \text{the dimension, } \text{dim}, \text{ of the array } \text{il} \text{ must be at least as large as the dimension of the array of the same name in } \text{nag}\_\text{superlu}\_\text{lu}\_\text{factorize} (f11mec).

\text{On entry: } \text{records the sparsity pattern of matrix } L \text{ as computed by } \text{nag}\_\text{superlu}\_\text{lu}\_\text{factorize} (f11mec).

6: \( \text{lval}[	ext{dim}] \) – const double \( \quad \) \text{Input}

\text{Note: } \text{the dimension, } \text{dim}, \text{ of the array } \text{lval} \text{ must be at least as large as the dimension of the array of the same name in } \text{nag}\_\text{superlu}\_\text{lu}\_\text{factorize} (f11mec).

\text{On entry: } \text{records the nonzero values of matrix } L \text{ and some nonzero values of matrix } U \text{ as computed by } \text{nag}\_\text{superlu}\_\text{lu}\_\text{factorize} (f11mec).

7: \( \text{iu}[\text{dim}] \) – const Integer \( \quad \) \text{Input}

\text{Note: } \text{the dimension, } \text{dim}, \text{ of the array } \text{iu} \text{ must be at least as large as the dimension of the array of the same name in } \text{nag}\_\text{superlu}\_\text{lu}\_\text{factorize} (f11mec).

\text{On entry: } \text{records the sparsity pattern of matrix } U \text{ as computed by } \text{nag}\_\text{superlu}\_\text{lu}\_\text{factorize} (f11mec).

8: \( \text{uval}[	ext{dim}] \) – const double \( \quad \) \text{Input}

\text{Note: } \text{the dimension, } \text{dim}, \text{ of the array } \text{uval} \text{ must be at least as large as the dimension of the array of the same name in } \text{nag}\_\text{superlu}\_\text{lu}\_\text{factorize} (f11mec).

\text{On entry: } \text{records some nonzero values of matrix } U \text{ as computed by } \text{nag}\_\text{superlu}\_\text{lu}\_\text{factorize} (f11mec).

9: \( \text{nrhs} \) – Integer \( \quad \) \text{Input}

\text{On entry: } nrhs, \text{ the number of right-hand sides in } B.

\text{Constraint: } nrhs \geq 0.

10: \( \text{b}[	ext{dim}] \) – double \( \quad \) \text{Input/Output}

\text{Note: } \text{the dimension, } \text{dim}, \text{ of the array } \text{b} \text{ must be at least}

\text{max}(1, \text{pdb} \times \text{nrhs}) \text{ when } \text{order} = \text{Nag\_ColMajor;}

\text{max}(1, \text{n} \times \text{pdb}) \text{ when } \text{order} = \text{Nag\_RowMajor.}

The \((i, j)\)th element of the matrix \( B \) is stored in

\( \text{b}[(j - 1) \times \text{pdb} + i - 1] \text{ when } \text{order} = \text{Nag\_ColMajor;} \)

\( \text{b}[(i - 1) \times \text{pdb} + j - 1] \text{ when } \text{order} = \text{Nag\_RowMajor.} \)

\text{On entry: } \text{the } \text{n} \text{ by } \text{nrhs} \text{ right-hand side matrix } B.

\text{On exit: } \text{the } \text{n} \text{ by } \text{nrhs} \text{ solution matrix } X.
11: \textbf{pdb} – Integer \hspace{1cm} \textit{Input}

\textit{On entry:} the stride separating row or column elements (depending on the value of \textbf{order}) in the array \textbf{b}.

\textit{Constraints:}

\begin{align*}
\text{if } \text{order} &= \text{Nag\_ColMajor}, & \text{pdb} \geq \max(1, n); \\
\text{if } \text{order} &= \text{Nag\_RowMajor}, & \text{pdb} \geq \max(1, \text{nrhs}).
\end{align*}

12: \textbf{fail} – NagError * \hspace{1cm} \textit{Input/Output}

The NAG error argument (see Section 3.6 in the Essential Introduction).

\section{6 Error Indicators and Warnings}

\textbf{NE\_ALLOC\_FAIL}

Dynamic memory allocation failed.
See Section 3.2.1.2 in the Essential Introduction for further information.

\textbf{NE\_BAD\_PARAM}

On entry, argument \langle value \rangle had an illegal value.

\textbf{NE\_INT}

On entry, \textbf{n} = \langle value \rangle.
Constraint: \textbf{n} \geq 0.

On entry, \textbf{nrhs} = \langle value \rangle.
Constraint: \textbf{nrhs} \geq 0.

On entry, \textbf{pdb} = \langle value \rangle.
Constraint: \textbf{pdb} > 0.

\textbf{NE\_INT\_2}

On entry, \textbf{pdb} = \langle value \rangle and \textbf{n} = \langle value \rangle.
Constraint: \textbf{pdb} \geq \max(1, \textbf{n}).

On entry, \textbf{pdb} = \langle value \rangle and \textbf{nrhs} = \langle value \rangle.
Constraint: \textbf{pdb} \geq \max(1, \textbf{nrhs}).

\textbf{NE\_INTERNAL\_ERROR}

An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please contact NAG for assistance.

An unexpected error has been triggered by this function. Please contact NAG.
See Section 3.6.6 in the Essential Introduction for further information.

\textbf{NE\_INVALID\_PERM\_COL}

Incorrect column permutations in array \textbf{iprm}.

\textbf{NE\_INVALID\_PERM\_ROW}

Incorrect Row Permutations in array \textbf{iprm}.

\textbf{NE\_NO\_LICENCE}

Your licence key may have expired or may not have been installed correctly.
See Section 3.6.5 in the Essential Introduction for further information.
7 Accuracy

For each right-hand side vector \( b \), the computed solution \( x \) is the exact solution of a perturbed system of equations \( (A + E)x = b \), where

\[
|E| \leq c(n)\epsilon|L||U|,
\]

\( c(n) \) is a modest linear function of \( n \), and \( \epsilon \) is the machine precision, when partial pivoting is used.

If \( \hat{x} \) is the true solution, then the computed solution \( x \) satisfies a forward error bound of the form

\[
\frac{\|x - \hat{x}\|_\infty}{\|x\|_\infty} \leq c(n) \text{cond}(A, x)\epsilon
\]

where \( \text{cond}(A, x) = \frac{\|A^{-1}\|\|A\|\|x\|_\infty}{\|x\|_\infty} \leq \text{cond}(A) = \frac{\|A^{-1}\|\|A\|_\infty}{\|\|A\|_\infty} \leq \kappa_\infty(A) \). Note that \( \text{cond}(A, x) \) can be much smaller than \( \text{cond}(A) \), and \( \text{cond}(A^T) \) can be much larger (or smaller) than \( \text{cond}(A) \).

Forward and backward error bounds can be computed by calling nag_superlu_refine_lu (f11mhc), and an estimate for \( \kappa_\infty(A) \) can be obtained by calling nag_superlu_condition_number_lu (f11mgc).

8 Parallelism and Performance

nag_superlu_solve_lu (f11mfc) is threaded by NAG for parallel execution in multithreaded implementations of the NAG Library.

nag_superlu_solve_lu (f11mfc) makes calls to BLAS and/or LAPACK routines, which may be threaded within the vendor library used by this implementation. Consult the documentation for the vendor library for further information.

Please consult the X06 Chapter Introduction for information on how to control and interrogate the OpenMP environment used within this function. Please also consult the Users’ Note for your implementation for any additional implementation-specific information.

9 Further Comments

nag_superlu_solve_lu (f11mfc) may be followed by a call to nag_superlu_refine_lu (f11mhc) to refine the solution and return an error estimate.

10 Example

This example solves the system of equations \( AX = B \), where

\[
A = \begin{pmatrix}
2.00 & 1.00 & 0 & 0 & 0 \\
0 & 0 & 1.00 & -1.00 & 0 \\
4.00 & 0 & 1.00 & 0 & 1.00 \\
0 & 0 & 0 & 1.00 & 2.00 \\
0 & -2.00 & 0 & 0 & 3.00
\end{pmatrix}
\text{ and } B = \begin{pmatrix}
1.56 & 3.12 \\
-0.25 & -0.50 \\
3.60 & 7.20 \\
1.33 & 2.66 \\
0.52 & 1.04
\end{pmatrix}.
\]

Here \( A \) is nonsymmetric and must first be factorized by nag_superlu_lu_factorize (f11mec).

10.1 Program Text

/* nag_superlu_solve_lu (f11mfc) Example Program. 
 * 
 * Copyright 2014 Numerical Algorithms Group.
 * 
 * Mark 8, 2005.
 * */

#include <stdio.h>
#include <nag.h>
#include <nagx04.h>
#include <nag_stdlib.h>
#include <nagf11.h>
int main(void)
{
    double flop, thresh;
    Integer exit_status = 0, i, j;
    Integer n, nnz, nnzl, nnzu, nrhs, nzlmx, nzlumx, nzumx;
    double *a = 0, *lval = 0, *uval = 0, *x = 0;
    Integer *icolzp = 0, *il = 0, *iprm = 0, *irowix = 0;
    Integer *iu = 0;
    /* Nag types */
    Nag_OrderType order = Nag_ColMajor;
    Nag_MatrixType matrix = Nag_GeneralMatrix;
    Nag_DiagType diag = Nag_NonUnitDiag;
    Nag_ColumnPermutationType ispec;
    Nag_TransType trans;
    NagError fail;

    INIT_FAIL(fail);

    printf("nag_superlu_solve_lu (f11mfc) Example Program Results\n\n");
    /* Skip heading in data file */
    #ifdef _WIN32
    scanf_s("%*[\n] ");
    #else
    scanf("%*[\n] ");
    #endif
    /* Read order of matrix and number of right hand sides */
    #ifdef _WIN32
    scanf_s("%"NAG_IFMT"%"NAG_IFMT"%*[\n] ", &n, &nrhs);
    #else
    scanf("%"NAG_IFMT"%"NAG_IFMT"%*[\n] ", &n, &nrhs);
    #endif
    /* Read the matrix A */
    if (!(icolzp = NAG_ALLOC(n+1, Integer)))
    {
        printf("Allocation failure\n");
        exit_status = -1;
        goto END;
    }
    for (i = 1; i <= n + 1; ++i)
    {
        #ifdef _WIN32
        scanf_s("%"NAG_IFMT"%*[\n] ", &icolzp[i - 1]);
        #else
        scanf("%"NAG_IFMT"%*[\n] ", &icolzp[i - 1]);
        #endif
    }
    nnz = icolzp[n] - 1;
    /* Allocate memory */
    if (!(irowix = NAG_ALLOC(nnz, Integer)) ||
        !(il = NAG_ALLOC(7*n+8*nnz+4, Integer)) ||
        !(iu = NAG_ALLOC(2*n+8*nnz+1, Integer)) ||
        !(lval = NAG_ALLOC(8*nnz, double)) ||
        !(uval = NAG_ALLOC(8*nnz, double)) ||
        !(iprm = NAG_ALLOC(7*n, Integer)) ||
        !(x = NAG_ALLOC(n*nrhs, double)))
    {
        printf("Allocation failure\n");
        exit_status = -1;
        goto END;
    }
    for (i = 1; i <= nnz; ++i)
    {
        #ifdef _WIN32
        scanf_s("%lf"NAG_IFMT"%*[\n] ", &a[i - 1], &irowix[i - 1]);
        #else
        scanf("%lf"NAG_IFMT"%*[\n] ", &a[i - 1], &irowix[i - 1]);
        #endif
    }
    /* Read the right hand sides */
    for (j = 1; j <= nrhs; ++j)
for (i = 1; i <= n; ++i)
#ifdef _WIN32
    scanf_s("%lf", &x[j*n + i - n - 1]);
#else
    scanf("%lf", &x[j*n + i - n - 1]);
#endif
#ifdef _WIN32
    scanf_s("%*[^
 ];
#else
    scanf("%*[^
 ]");
#endif
/* Calculate COLAMD permutation */
ispec = Nag_Sparse_Colamd;
/* nag_superlu_column_permutation (f11mdc).
 * Real sparse nonsymmetric linear systems, setup for
 * nag_superlu_lu_factorize (f11mec)
 */
nag_superlu_column_permutation(ispec, n, icolzp, irowix, iprm, &fail);
if (fail.code != NE_NOERROR)
{
    printf("Error from nag_superlu_column_permutation (f11mdc).\n" fail.message);
    exit_status = 1;
goto END;
}
/* Factorise */
thresh = 1.;
nzlmx = 8*nnz;
nzlumx = 8*nnz;
nzumx = 8*nnz;
/* nag_superlu_lu_factorize (f11mec).
 * LU factorization of real sparse matrix
 */
nag_superlu_lu_factorize(n, irowix, a, iprm, thresh, nzlmx, &nzlumx, nzumx,
il, lval, iu, uval, &nnzl, &nnzu, &flop, &fail);
if (fail.code != NE_NOERROR)
{
    printf("Error from nag_superlu_lu_factorize (f11mec).\n" fail.message);
    exit_status = 1;
goto END;
}
/* Solve */
trans = Nag_NoTrans;
/* nag_superlu_solve_lu (f11mfc).
 * Solution of real sparse simultaneous linear equations
 * (coefficient matrix already factorized)
 */
nag_superlu_solve_lu(order, trans, n, iprm, il, lval, iu, uval, nrhs, x,
n, &fail);
if (fail.code != NE_NOERROR)
{
    printf("Error from nag_superlu_solve_lu (f11mfc).\n" fail.message);
    exit_status = 1;
goto END;
}
/* Output results */
printf("\n");
/* nag_gen_real_mat_print (x04cac).
 * Print real general matrix (easy-to-use)
 */
fflush(stdout);
nag_gen_real_mat_print(order, matrix, diag, n, nrhs,
x, n, "Solutions", 0, &fail);
if (fail.code != NE_NOERROR)
printf("Error from nag_gen_real_mat_print (x04cac).\n%s\n", fail.message);
    exit_status = 1;
    goto END;
}

END:
NAG_FREE(a);
NAG_FREE(lval);
NAG_FREE(uval);
NAG_FREE(x);
NAG_FREE(icolzp);
NAG_FREE(il);
NAG_FREE(iprm);
NAG_FREE(irowix);
NAG_FREE(iu);

    return exit_status;
}

10.2 Program Data

nag_superlu_solve_lu (f11mfc) Example Program Data

5 2  n, nrhs
1
3
5
7

icolzp(i) i=0..n
2. 1
4. 3
1. 1
-2. 5
1. 2
1. 3
-1. 2
1. 4
1. 3
2. 4
3. 5  a(i), irowix(i) i=0..nnz-1
1.56 -.25 3.6 1.33 .52
3.12 -.50 7.2 2.66 1.04 matrix x

10.3 Program Results

nag_superlu_solve_lu (f11mfc) Example Program Results

Solutions

<table>
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<tr>
<th></th>
<th>1</th>
<th>2</th>
</tr>
</thead>
<tbody>
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<td>0.7000</td>
<td>1.4000</td>
</tr>
<tr>
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<td>0.1600</td>
<td>0.3200</td>
</tr>
<tr>
<td>3</td>
<td>0.5200</td>
<td>1.0400</td>
</tr>
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<td>1.5400</td>
</tr>
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<td>0.2800</td>
<td>0.5600</td>
</tr>
</tbody>
</table>