NAG Library Function Document

nag_dsbtrd (f08hec)

1 Purpose
nag_dsbtrd (f08hec) reduces a real symmetric band matrix to tridiagonal form.

2 Specification
#include <nag.h>
#include <nagf08.h>

void nag_dsbtrd (Nag_OrderType order, Nag_VectType vect, Nag_UploType uplo,
Integer n, Integer kd, double ab[], Integer pdab, double d[],
double e[], double q[], Integer pdq, NagError *fail)

3 Description
nag_dsbtrd (f08hec) reduces a symmetric band matrix $A$ to symmetric tridiagonal form $T$ by an
orthogonal similarity transformation:

$$T = Q^T A Q.$$ 

The orthogonal matrix $Q$ is determined as a product of Givens rotation matrices, and may be formed
explicitly by the function if required.

The function uses a vectorizable form of the reduction, due to Kaufman (1984).

4 References

5 Arguments
1: order – Nag_OrderType

On entry: the order argument specifies the two-dimensional storage scheme being used, i.e., row-
major ordering or column-major ordering. C language defined storage is specified by
order ¼ Nag_RowMajor. See Section 3.2.1.3 in the Essential Introduction for a more detailed
explanation of the use of this argument.

Constraint: order ¼ Nag_RowMajor or Nag_ColMajor.

2: vect – Nag_VectType

On entry: indicates whether $Q$ is to be returned.

vect ¼ Nag_FormQ
$Q$ is returned.

vect ¼ Nag_UpdateQ
$Q$ is updated (and the array q must contain a matrix on entry).

vect ¼ Nag_DoNotForm
$Q$ is not required.

Constraint: vect ¼ Nag_FormQ, Nag_UpdateQ or Nag_DoNotForm.
3: \textbf{uplo} – Nag_UploType \hspace{1cm} \textit{Input}

\textit{On entry}: indicates whether the upper or lower triangular part of $A$ is stored.

\textbf{uplo} = Nag_Upper

The upper triangular part of $A$ is stored.

\textbf{uplo} = Nag_Lower

The lower triangular part of $A$ is stored.

\textit{Constraint}: \textbf{uplo} = Nag_Upper or Nag_Lower.

4: $n$ – Integer \hspace{1cm} \textit{Input}

\textit{On entry}: $n$, the order of the matrix $A$.

\textit{Constraint}: $n \geq 0$.

5: $kd$ – Integer \hspace{1cm} \textit{Input}

\textit{On entry}: if \textbf{uplo} = Nag_Upper, the number of superdiagonals, $k_d$, of the matrix $A$.

If \textbf{uplo} = Nag_Lower, the number of subdiagonals, $k_d$, of the matrix $A$.

\textit{Constraint}: $kd \geq 0$.

6: $ab[dim]$ – double \hspace{1cm} \textit{Input/Output}

\textit{Note}: the dimension, \textit{dim}, of the array \textbf{ab} must be at least $\max(1, pdab \times n)$.

\textit{On entry}: the upper or lower triangle of the $n$ by $n$ symmetric band matrix $A$.

This is stored as a notional two-dimensional array with row elements or column elements stored contiguously. The storage of elements of $A_{ij}$, depends on the \textbf{order} and \textbf{uplo} arguments as follows:

- if \textbf{order} = Nag_ColMajor and \textbf{uplo} = Nag_Upper,
  \hspace{1cm} $A_{ij}$ is stored in $ab[k_d + i - j + (j - 1) \times pdab]$, for $j = 1, \ldots, n$ and $i = \max(1, j - k_d), \ldots, j$;
- if \textbf{order} = Nag_ColMajor and \textbf{uplo} = Nag_Lower,
  \hspace{1cm} $A_{ij}$ is stored in $ab[i - j + (j - 1) \times pdab]$, for $j = 1, \ldots, n$ and $i = j, \ldots, \min(n, j + k_d)$;
- if \textbf{order} = Nag_RowMajor and \textbf{uplo} = Nag_Upper,
  \hspace{1cm} $A_{ij}$ is stored in $ab[j - i + (i - 1) \times pdab]$, for $i = 1, \ldots, n$ and $j = i, \ldots, \min(n, i + k_d)$;
- if \textbf{order} = Nag_RowMajor and \textbf{uplo} = Nag_Lower,
  \hspace{1cm} $A_{ij}$ is stored in $ab[k_d + j - i + (i - 1) \times pdab]$, for $i = 1, \ldots, n$ and $j = \max(1, i - k_d), \ldots, i$.

\textit{On exit}: \textbf{ab} is overwritten by values generated during the reduction to tridiagonal form.

The first superdiagonal or subdiagonal and the diagonal of the tridiagonal matrix $T$ are returned in \textbf{ab} using the same storage format as described above.

7: $pdab$ – Integer \hspace{1cm} \textit{Input}

\textit{On entry}: the stride separating row or column elements (depending on the value of \textbf{order}) of the matrix $A$ in the array \textbf{ab}.

\textit{Constraint}: $pdab \geq \max(1, kd + 1)$.

8: $d[n]$ – double \hspace{1cm} \textit{Output}

\textit{On exit}: the diagonal elements of the tridiagonal matrix $T$. 

\textit{f08hec} \hspace{1cm} NAG Library Manual
9:  $e[n-1]$ – double  
    Output
    On exit: the off-diagonal elements of the tridiagonal matrix $T$.

10:  $q[dim]$ – double  
    Input/Output
    Note: the dimension, $dim$, of the array $q$ must be at least
    $\max(1, pdq \times n)$ when $\text{vect} = \text{Nag\_FormQ}$ or $\text{Nag\_UpdateQ}$;  
    1 when $\text{vect} = \text{Nag\_DoNotForm}$.
    The $(i, j)$th element of the matrix $Q$ is stored in
    
    $q[(j-1) \times pdq + i - 1]$ when $\text{order} = \text{Nag\_ColMajor}$;
    $q[(i-1) \times pdq + j - 1]$ when $\text{order} = \text{Nag\_RowMajor}$.

    On entry: if $\text{vect} = \text{Nag\_UpdateQ}$, $q$ must contain the matrix formed in a previous stage of the
    reduction (for example, the reduction of a banded symmetric-definite generalized eigenproblem); otherwise $q$
    need not be set.

    On exit: if $\text{vect} = \text{Nag\_FormQ}$ or $\text{Nag\_UpdateQ}$, the $n$ by $n$ matrix $Q$.
    If $\text{vect} = \text{Nag\_DoNotForm}$, $q$ is not referenced.

11:  $pdq$ – Integer  
    Input
    On entry: the stride separating row or column elements (depending on the value of $\text{order}$) in the
    array $q$.
    Constraints:
    
    if $\text{vect} = \text{Nag\_FormQ}$ or $\text{Nag\_UpdateQ}$, $pdq \geq \max(1, n)$;
    if $\text{vect} = \text{Nag\_DoNotForm}$, $pdq \geq 1$.

12:  $fail$ – NagError *  
    Input/Output
    The NAG error argument (see Section 3.6 in the Essential Introduction).

6  Error Indicators and Warnings

NE_ALLOC_FAIL
    Dynamic memory allocation failed.
    See Section 3.2.1.2 in the Essential Introduction for further information.

NE_BAD_PARAM
    On entry, argument $\langle value\rangle$ had an illegal value.

NE_ENUM_INT_2
    On entry, $\text{vect} = \langle value\rangle$, $pdq = \langle value\rangle$ and $n = \langle value\rangle$.
    Constraint: if $\text{vect} = \text{Nag\_FormQ}$ or $\text{Nag\_UpdateQ}$, $pdq \geq \max(1, n)$;
    if $\text{vect} = \text{Nag\_DoNotForm}$, $pdq \geq 1$.

NE_INT
    On entry, $kd = \langle value\rangle$.
    Constraint: $kd \geq 0$.

    On entry, $n = \langle value\rangle$.
    Constraint: $n \geq 0$.

    On entry, $pdab = \langle value\rangle$.
    Constraint: $pdab > 0$. 
On entry, \(pdq = \langle value\rangle\).
Constraint: \(pdq > 0\).

**NE_INT_2**
On entry, \(pdab = \langle value\rangle\) and \(kd = \langle value\rangle\).
Constraint: \(pdab \geq \max(1, kd + 1)\).

**NE_INTERNAL_ERROR**
An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please contact NAG for assistance.
An unexpected error has been triggered by this function. Please contact NAG.
See Section 3.6.6 in the Essential Introduction for further information.

**NE_NO_LICENCE**
Your licence key may have expired or may not have been installed correctly.
See Section 3.6.5 in the Essential Introduction for further information.

7 **Accuracy**
The computed tridiagonal matrix \(T\) is exactly similar to a nearby matrix \((A + E)\), where
\[\|E\|_2 \leq c(n)e\|A\|_2,\]
\(c(n)\) is a modestly increasing function of \(n\), and \(e\) is the *machine precision*.
The elements of \(T\) themselves may be sensitive to small perturbations in \(A\) or to rounding errors in the computation, but this does not affect the stability of the eigenvalues and eigenvectors.
The computed matrix \(Q\) differs from an exactly orthogonal matrix by a matrix \(E\) such that
\[\|E\|_2 = O(e),\]
where \(e\) is the *machine precision*.

8 **Parallelism and Performance**
\texttt{nag_dsbtrd (f08hec)} is threaded by NAG for parallel execution in multithreaded implementations of the NAG Library.
\texttt{nag_dsbtrd (f08hec)} makes calls to BLAS and/or LAPACK routines, which may be threaded within the vendor library used by this implementation. Consult the documentation for the vendor library for further information.
Please consult the X06 Chapter Introduction for information on how to control and interrogate the OpenMP environment used within this function. Please also consult the Users’ Note for your implementation for any additional implementation-specific information.

9 **Further Comments**
The total number of floating-point operations is approximately \(6n^2k\) if \textbf{vect} = Nag_DoNotForm with \(3n^3(k - 1)/k\) additional operations if \textbf{vect} = Nag_Form\(Q\).
The complex analogue of this function is \texttt{nag_zhbtrd (f08hsc)}. 
10  Example

This example computes all the eigenvalues and eigenvectors of the matrix $A$, where

$$A = \begin{pmatrix}
4.99 & 0.04 & 0.22 & 0.00 \\
0.04 & 1.05 & -0.79 & 1.04 \\
0.22 & -0.79 & -2.31 & -1.30 \\
0.00 & 1.04 & -1.30 & -0.43
\end{pmatrix}.$$  

Here $A$ is symmetric and is treated as a band matrix. The program first calls nag_dsbtrd (f08hec) to reduce $A$ to tridiagonal form $T$, and to form the orthogonal matrix $Q$; the results are then passed to nag_dsteqr (f08jec) which computes the eigenvalues and eigenvectors of $A$.

10.1  Program Text

```c
/* nag_dsbtrd (f08hec) Example Program. */
 *
 * Copyright 2014 Numerical Algorithms Group.
 *
 */

#include <stdio.h>
#include <nag.h>
#include <nag_stdlib.h>
#include <nagf08.h>
#include <nagx04.h>

int main(void)
{
    /* Scalars */
    Integer i, j, k, kd, n, pdab, pdz, d_len, e_len;
    Integer exit_status = 0;
    NagError fail;
    Nag_UploType uplo;
    Nag_OrderType order;
    /* Arrays */
    char nag_enum_arg[40];
    double *ab = 0, *d = 0, *e = 0, *z = 0;

    INIT_FAIL(fail);

    printf("nag_dsbtrd (f08hec) Example Program Results\n\n");

    /* Skip heading in data file */
    #ifdef _WIN32
        scanf_s("%*[^\n] ");
    #else
        scanf("%*[^\n] ");
    #endif

    pdab = kd + 1;
    pdz = n;

    ...
/* Allocate memory */
if (!(ab = NAG_ALLOC(pdab * n, double)) ||
    !(d = NAG_ALLOC(d_len, double)) ||
    !(e = NAG_ALLOC(e_len, double)) ||
    !(z = NAG_ALLOC(pdz * n, double)))
{
    printf("Allocation failure\n");
    exit_status = -1;
    goto END;
}

/* Read A from data file */
#ifdef _WIN32
    scanf_s("%39s%*[\n ] ", nag_enum_arg, _countof(nag_enum_arg));
#else
    scanf("%39s%*[\n ] ", nag_enum_arg);
#endif
/* nag_enum_name_to_value (x04nac).
* Converts NAG enum member name to value
*/
uplo = (Nag_UploType) nag_enum_name_to_value(nag_enum_arg);
k = k + 1;
if (uplo == Nag_Upper)
{
    for (i = 1; i <= n; ++i)
    {
        for (j = i; j <= MIN(i + kd, n); ++j)
#ifdef _WIN32
            scanf_s("%lf", &AB_UPPER(i, j));
#else
            scanf("%lf", &AB_UPPER(i, j));
#endif
    }
#ifdef _WIN32
    scanf_s("%*[\n ] ");
#else
    scanf("%*[\n ] ");
#endif
    else
{
    for (i = 1; i <= n; ++i)
    {
        for (j = MAX(1, i - kd); j <= i; ++j)
#ifdef _WIN32
            scanf_s("%lf", &AB_LOWER(i, j));
#else
            scanf("%lf", &AB_LOWER(i, j));
#endif
    }
#ifdef _WIN32
    scanf_s("%*[\n ] ");
#else
    scanf("%*[\n ] ");
#endif
}
/* Reduce A to tridiagonal form */
/* nag_dsbtrd (f08hec).
* Orthogonal reduction of real symmetric band matrix to
* symmetric tridiagonal form
*/
nag_dsbtrd(order, Nag_FormQ, uplo, n, kd, ab, pdab, d, e, z, pdz, &fail);
if (fail.code != NE_NOERROR)
{
    printf("Error from nag_dsbtrd (f08hec).\n%s\n", fail.message);
    exit_status = 1;
}
/* Calculate all the eigenvalues and eigenvectors of A */
/* nag_dsteqr (f08jec).
* All eigenvalues and eigenvectors of real symmetric
* tridiagonal matrix, reduced from real symmetric matrix
* using implicit QL or QR
*/
nag_dsteqr(order, Nag_UpdateZ, n, d, e, z, pdz, &fail);
if (fail.code != NE_NOERROR)
{
    printf("Error from nag_dsteqr (f08jec).
%s
", fail.message);
    exit_status = 1;
    goto END;
}
/* Normalize the eigenvectors */
for(j=1; j<=n; j++)
{
    for(i=n; i>=1; i--)
    {
        Z(i, j) = Z(i, j) / Z(1,j);
    }
}
/* Print eigenvalues and eigenvectors */
printf("Eigenvalues\n");
for (i = 1; i <= n; ++i)
    printf("%8.4f%s", d[i-1], i%8 == 0?"\n":" ");
printf(\n"");
/* nag_gen_real_mat_print (x04cac).
* Print real general matrix (easy-to-use)
*/
fflush(stdout);
nag_gen_real_mat_print(order, Nag_GeneralMatrix, Nag_NonUnitDiag, n, n,
z, pdz, "Eigenvectors", 0, &fail);
if (fail.code != NE_NOERROR)
{
    printf("Error from nag_gen_real_mat_print (x04cac).
%s
", fail.message);
    exit_status = 1;
    goto END;
}
END:
NAG_FREE(ab);
NAG_FREE(d);
NAG_FREE(e);
NAG_FREE(z);
return exit_status;

10.2 Program Data

nag_dsbtrd (f08hec) Example Program Data
4 2 :Values of n and kd
Nag_Lower :Value of uplo
4.99
0.04 1.05
0.22 -0.79 -2.31
1.04 -1.30 -0.43 :End of matrix A

10.3 Program Results

nag_dsbtrd (f08hec) Example Program Results

Eigenvalues
-2.9943 -0.7000 1.9974 4.9969

Eigenvectors
<table>
<thead>
<tr>
<th></th>
<th>1</th>
<th>2</th>
<th>3</th>
<th>4</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>1.0000</td>
<td>1.0000</td>
<td>1.0000</td>
<td>1.0000</td>
</tr>
<tr>
<td>2</td>
<td>-2.6092</td>
<td>-36.0739</td>
<td>71.4695</td>
<td>0.0020</td>
</tr>
<tr>
<td>3</td>
<td>-35.8180</td>
<td>-19.3048</td>
<td>-26.5971</td>
<td>0.0311</td>
</tr>
<tr>
<td>4</td>
<td>-17.1000</td>
<td>45.9991</td>
<td>44.8645</td>
<td>-0.0071</td>
</tr>
</tbody>
</table>