nag_zpbsv (f07hnc) computes the solution to a complex system of linear equations

\[ AX = B, \]

where \( A \) is an \( n \) by \( n \) Hermitian positive definite band matrix of bandwidth \((2k_d + 1)\) and \( X \) and \( B \) are \( n \) by \( r \) matrices.

nag_zpbsv (f07hnc) uses the Cholesky decomposition to factor \( A \) as \( A = U^H U \) if \( \text{uplo} = \text{Nag}_\text{Upper} \) or \( A = L L^H \) if \( \text{uplo} = \text{Nag}_\text{Lower} \), where \( U \) is an upper triangular band matrix, and \( L \) is a lower triangular band matrix, with the same number of superdiagonals or subdiagonals as \( A \). The factored form of \( A \) is then used to solve the system of equations \( AX = B \).

**References**


**Arguments**

1. \textit{order} – Nag_OrderType  
   \textit{Input}  
   \textit{On entry:} the \textit{order} argument specifies the two-dimensional storage scheme being used, i.e., row-major ordering or column-major ordering. C language defined storage is specified by \textit{order} = Nag_RowMajor. See Section 3.2.1.3 in the Essential Introduction for a more detailed explanation of the use of this argument.  
   \textit{Constraint:} \textit{order} = Nag_RowMajor or Nag_ColMajor.

2. \textit{uplo} – Nag_UploType  
   \textit{Input}  
   \textit{On entry:} if \textit{uplo} = Nag_Upper, the upper triangle of \( A \) is stored. \n   If \textit{uplo} = Nag_Lower, the lower triangle of \( A \) is stored.  
   \textit{Constraint:} \textit{uplo} = Nag_Upper or Nag_Lower.
3: \( n \) – Integer

*Input*

*On entry:* \( n \), the number of linear equations, i.e., the order of the matrix \( A \).

*Constraint:* \( n \geq 0 \).

4: \( kd \) – Integer

*Input*

*On entry:* \( kd \), the number of superdiagonals of the matrix \( A \) if \( \text{uplo} = \text{Nag}\_\text{Upper} \), or the number of subdiagonals if \( \text{uplo} = \text{Nag}\_\text{Lower} \).

*Constraint:* \( kd \geq 0 \).

5: \( nrhs \) – Integer

*Input*

*On entry:* \( r \), the number of right-hand sides, i.e., the number of columns of the matrix \( B \).

*Constraint:* \( nrhs \geq 0 \).

6: \( \text{ab}[\dim] \) – Complex

*Input/Output*

*Note:* the dimension, \( \dim \), of the array \( \text{ab} \) must be at least \( \max(1, \text{pdab} \times n) \).

*On entry:* the upper or lower triangle of the Hermitian band matrix \( A \).

This is stored as a notional two-dimensional array with row elements or column elements stored contiguously. The storage of elements of \( A_{ij} \), depends on the order and uplo arguments as follows:

\[
\begin{align*}
\text{if order} &= \text{Nag}\_\text{ColMajor} \text{ and uplo} = \text{Nag}\_\text{Upper}, \\
A_{ij} \text{ is stored in } \text{ab}[k_d + i - j + (j - 1) \times \text{pdab}], & \text{ for } j = 1, \ldots, n \text{ and } i = \max(1, j - k_d), \ldots, j; \\
\text{if order} &= \text{Nag}\_\text{ColMajor} \text{ and uplo} = \text{Nag}\_\text{Lower}, \\
A_{ij} \text{ is stored in } \text{ab}[i - j + (j - 1) \times \text{pdab}], & \text{ for } j = 1, \ldots, n \text{ and } i = j, \ldots, \min(n, j + k_d); \\
\text{if order} &= \text{Nag}\_\text{RowMajor} \text{ and uplo} = \text{Nag}\_\text{Upper}, \\
A_{ij} \text{ is stored in } \text{ab}[j - i + (i - 1) \times \text{pdab}], & \text{ for } i = 1, \ldots, n \text{ and } j = i, \ldots, \min(n, i + k_d); \\
\text{if order} &= \text{Nag}\_\text{RowMajor} \text{ and uplo} = \text{Nag}\_\text{Lower}, \\
A_{ij} \text{ is stored in } \text{ab}[k_d + j - i + (i - 1) \times \text{pdab}], & \text{ for } i = 1, \ldots, n \text{ and } j = \max(1, i - k_d), \ldots, i.
\end{align*}
\]

*On exit:* if \( \text{fail.code} = \text{NE}_\text{NOERROR} \), the triangular factor \( U \) or \( L \) from the Cholesky factorization \( A = U^H U \) or \( A = L L^H \) of the band matrix \( A \), in the same storage format as \( A \).

7: \( \text{pdab} \) – Integer

*Input*

*On entry:* the stride separating row or column elements (depending on the value of order) of the matrix \( A \) in the array \( \text{ab} \).

*Constraint:* \( \text{pdab} \geq kd + 1 \).

8: \( \text{b}[\dim] \) – Complex

*Input/Output*

*Note:* the dimension, \( \dim \), of the array \( \text{b} \) must be at least

\[
\max(1, \text{pdab} \times nrhs) \text{ when order} = \text{Nag}\_\text{ColMajor}; \\
\max(1, n \times \text{pdab}) \text{ when order} = \text{Nag}\_\text{RowMajor}.
\]

The \((i, j)\)th element of the matrix \( B \) is stored in

\[
\begin{align*}
\text{b}[j - 1] \times \text{pdab} + i - 1] & \text{ when order} = \text{Nag}\_\text{ColMajor}; \\
\text{b}[i - 1] \times \text{pdab} + j - 1] & \text{ when order} = \text{Nag}\_\text{RowMajor}.
\end{align*}
\]

*On entry:* the \( n \) by \( r \) right-hand side matrix \( B \).

*On exit:* if \( \text{fail.code} = \text{NE}_\text{NOERROR} \), the \( n \) by \( r \) solution matrix \( X \).
9: pdb – Integer

*Input*

*On entry:* the stride separating row or column elements (depending on the value of *order*) in the array b.

*Constraints:*

if *order* = Nag_ColMajor, *pdb* ≥ max(1, *n*);
if *order* = Nag_RowMajor, *pdb* ≥ max(1, *nrhs*).

10: fail – NagError *

*Input/Output*

The NAG error argument (see Section 3.6 in the Essential Introduction).

## 6 Error Indicators and Warnings

### NE_ALLOC_FAIL

Dynamic memory allocation failed.
See Section 3.2.1.2 in the Essential Introduction for further information.

### NE_BAD_PARAM

On entry, argument ⟨value⟩ had an illegal value.

### NE_INT

On entry, *kd* = ⟨value⟩.
Constraint: *kd* ≥ 0.

On entry, *n* = ⟨value⟩.
Constraint: *n* ≥ 0.

On entry, *nrhs* = ⟨value⟩.
Constraint: *nrhs* ≥ 0.

On entry, *pdb* = ⟨value⟩.
Constraint: *pdb* > 0.

On entry, *pdb* = ⟨value⟩.
Constraint: *pdb* > 0.

### NE_INT_2

On entry, *pdb* = ⟨value⟩ and *kd* = ⟨value⟩.
Constraint: *pdb* ≥ *kd* + 1.

On entry, *pdb* = ⟨value⟩ and *n* = ⟨value⟩.
Constraint: *pdb* ≥ max(1, *n*).

On entry, *pdb* = ⟨value⟩ and *nrhs* = ⟨value⟩.
Constraint: *pdb* ≥ max(1, *nrhs*).

### NE_INTERNAL_ERROR

An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please contact NAG for assistance.

An unexpected error has been triggered by this function. Please contact NAG.
See Section 3.6.6 in the Essential Introduction for further information.

### NE_MAT_NOT_POS_DEF

The leading minor of order ⟨value⟩ of A is not positive definite, so the factorization could not be completed, and the solution has not been computed.
7 Accuracy

The computed solution for a single right-hand side, $\hat{x}$, satisfies an equation of the form

$$(A + E)\hat{x} = b,$$

where

$$\|E\|_1 = O(\epsilon)\|A\|_1$$

and $\epsilon$ is the machine precision. An approximate error bound for the computed solution is given by

$$\frac{\|\hat{x} - x\|_1}{\|x\|_1} \leq \kappa(A)\frac{\|E\|_1}{\|A\|_1},$$

where $\kappa(A) = \|A^{-1}\|_1\|A\|_1$, the condition number of $A$ with respect to the solution of the linear equations. See Section 4.4 of Anderson et al. (1999) for further details.

nag_zpbsv (f07hpc) is a comprehensive LAPACK driver that returns forward and backward error bounds and an estimate of the condition number. Alternatively, nag_herm_posdef_band_lin_solve (f04cfc) solves $Ax = b$ and returns a forward error bound and condition estimate. nag_herm_posdef_band_lin_solve (f04cfc) calls nag_zpbsv (f07hnc) to solve the equations.

8 Parallelism and Performance

nag_zpbsv (f07hnc) is threaded by NAG for parallel execution in multithreaded implementations of the NAG Library.

nag_zpbsv (f07hnc) makes calls to BLAS and/or LAPACK routines, which may be threaded within the vendor library used by this implementation. Consult the documentation for the vendor library for further information.

Please consult the X06 Chapter Introduction for information on how to control and interrogate the OpenMP environment used within this function. Please also consult the Users’ Note for your implementation for any additional implementation-specific information.

9 Further Comments

When $n \gg k$, the total number of floating-point operations is approximately $4n(k + 1)^2 + 16nk r$, where $k$ is the number of superdiagonals and $r$ is the number of right-hand sides.

The real analogue of this function is nag_dpbsv (f07hac).

10 Example

This example solves the equations

$$Ax = b,$$

where $A$ is the Hermitian positive definite band matrix

$$A = \begin{pmatrix} 9.39 & 1.08 - 1.73i & 0 & 0 \\ 1.08 + 1.73i & 1.69 & -0.04 + 0.29i & 0 \\ 0 & -0.04 - 0.29i & 2.65 & -0.33 + 2.24i \\ 0 & 0 & -0.33 - 2.24i & 2.17 \end{pmatrix},$$

and
\[ b = \begin{pmatrix} -12.42 + 68.42i \\ -9.93 + 0.88i \\ -27.30 - 0.01i \\ 5.31 + 23.63i \end{pmatrix}. \]

Details of the Cholesky factorization of \( A \) are also output.

10.1 Program Text

/* nag_zpbsv (f07hnc) Example Program. */
* * Copyright 2014 Numerical Algorithms Group. *
* * Mark 23, 2011. */

#include <stdio.h>
#include <nag.h>
#include <nagx04.h>
#include <nag_stdlib.h>
#include <nagf07.h>

int main(void)
{
    /* Scalars */
    Integer exit_status = 0, i, j, kd, n, nrhs, pdab, pdb;

    /* Arrays */
    Complex *ab = 0, *b = 0;
    char nag_enum_arg[40];

    /* Nag Types */
    NagError fail;
    Nag_UploType uplo;
    Nag_OrderType order;

    #ifdef NAG_COLUMN_MAJOR
    #define AB_UPPER(I, J) ab[(J-1)*pdab + kd + I - J]
    #define AB_LOWER(I, J) ab[(J-1)*pdab + I - J]
    #define B(I, J) b[(J-1)*pdb + I - 1]
    order = Nag_ColMajor;
    #else
    #define AB_UPPER(I, J) ab[(I-1)*pdab + J - I]
    #define AB_LOWER(I, J) ab[(I-1)*pdab + kd + J - I]
    #define B(I, J) b[(I-1)*pdb + J - 1]
    order = Nag_RowMajor;
    #endif

    INIT_FAIL(fail);

    printf("nag_zpbsv (f07hnc) Example Program Results\n\n");

    /* Skip heading in data file */
    #ifdef _WIN32
    scanf_s("%*[\n]");
    #else
    scanf("%*[\n]");
    #endif

    #ifdef _WIN32
    scanf_s("%"NAG_IFMT"%"NAG_IFMT"%"NAG_IFMT"%*[\n]", &n, &kd, &nrhs);
    #else
    scanf("%"NAG_IFMT"%"NAG_IFMT"%"NAG_IFMT"%*[\n]", &n, &kd, &nrhs);
    #endif

    if (n < 0 || kd < 0 || nrhs < 0)
    {
        printf("Invalid n, kd or nrhs\n");
        exit_status = 1;
    }
ifdef _WIN32
scanf_s(" %39s%[\n]", nag_enum_arg, _countof(nag_enum_arg));
#else
scanf(" %39s%[\n]", nag_enum_arg);
#endif
/* nag_enum_name_to_value (x04nac).
* Converts NAG enum member name to value
*/
uplo = (Nag_UploType) nag_enum_name_to_value(nag_enum_arg);

/* Allocate memory */
if (!(ab = NAG_ALLOC((kd+1) * n, Complex)) ||
!(b = NAG_ALLOC(n*nrhs, Complex)))
{
    printf("Allocation failure\n");
    exit_status = -1;
    goto END;
}
pdab = kd+1;
ifdef NAG_COLUMN_MAJOR
    pdb = n;
#else
    pdb = nrhs;
#endif

/* Read the upper or lower triangular part of the band matrix A
* from data file */
if (uplo == Nag_Upper)
    for (i = 1; i <= n; ++i)
        for (j = i; j <= MIN(n, i + kd); ++j)
#ifdef _WIN32
            scanf_s(" ( %lf , %lf )", &AB_UPPER(i, j).re, &AB_UPPER(i, j).im);
#else
            scanf(" ( %lf , %lf )", &AB_UPPER(i, j).re, &AB_UPPER(i, j).im);
#endif
else
    for (i = 1; i <= n; ++i)
        for (j = MAX(1, i - kd); j <= i; ++j)
#ifdef _WIN32
            scanf_s(" ( %lf , %lf )", &AB_UPPER(i, j).re, &AB_UPPER(i, j).im);
#else
            scanf(" ( %lf , %lf )", &AB_UPPER(i, j).re, &AB_UPPER(i, j).im);
#endif
#ifdef _WIN32
    scanf_s("%*\[\n\]);
#else
    scanf("%*\[\n\]);
#endif

/* Read b from data file */
for (i = 1; i <= n; ++i)
    for (j = 1; j <= nrhs; ++j)
#ifdef _WIN32
        scanf_s(" ( %lf , %lf )", &B(i, j).re, &B(i, j).im);
#else
        scanf(" ( %lf , %lf )", &B(i, j).re, &B(i, j).im);
#endif
#ifdef _WIN32
    scanf_s("%*\[\n\]);
#else
    scanf("%*\[\n\]);
#endif

/* Solve the equations Ax = b for x using nag_zpbsv (f07hnc). */
if (fail.code != NE_NOERROR)
{
```c
printf("Error from nag_zpbsv (f07hnc).\n\n", fail.message);
exit_status = 1;
goto END;
}
/* Print solution */
printf("Solution\n");
for (i = 1; i <= n; ++i)
{
    for (j = 1; j <= nrhs; ++j)
    {
        printf("(%7.4f, %7.4f)%s", B(i, j).re, B(i, j).im, j%4 == 0?"\n":" ");
        printf("\n");
    }
}
printf("\n");
/* Print details of factorization using */
*nag_band_complx_mat_print_comp (x04dfc).
*/
fflush(stdout);
if (uplo == Nag_Upper)
    nag_band_complx_mat_print_comp(order, n, n, 0, kd, ab, pdab,
        Nag_BracketForm, "%7.4f",
        "Cholesky factor U", Nag_IntegerLabels, 0,
        Nag_IntegerLabels, 0, 80, 0, 0, &fail);
else
    nag_band_complx_mat_print_comp(order, n, n, kd, 0, ab, pdab,
        Nag_BracketForm, "%7.4f",
        "Cholesky factor L", Nag_IntegerLabels, 0,
        Nag_IntegerLabels, 0, 80, 0, 0, &fail);
if (fail.code != NE_NOERROR)
{
    printf("Error from nag_band_complx_mat_print_comp (x04dfc).
       fail.message); 
    exit_status = 1;
    goto END;
}
END:
NAG_FREE(ab);
NAG_FREE(b);
return exit_status;
}
#endif AB_UPPER
#endif AB_LOWER
#endif B

10.2 Program Data

nag_zpbsv (f07hnc) Example Program Data

nag_zpbsv (f07hnc) Example Program Data
nag_zpbsv (f07hnc) Example Program Data

10.3 Program Results

nag_zpbsv (f07hnc) Example Program Results

Solution
(-1.0000, 8.0000)
(2.0000, -3.0000)
(-4.0000, -5.0000)
(7.0000, 6.0000)

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<p>| | | | |</p>
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<tr>
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<th></th>
<th></th>
<th></th>
</tr>
</thead>
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<td>1</td>
<td>(3.0643, 0.0000)</td>
<td>(0.3524, -0.5646)</td>
<td></td>
</tr>
<tr>
<td>2</td>
<td>(1.1167, 0.0000)</td>
<td>(-0.0358, 0.2597)</td>
<td></td>
</tr>
<tr>
<td>3</td>
<td>(1.6066, 0.0000)</td>
<td>(-0.2054, 1.3942)</td>
<td></td>
</tr>
<tr>
<td>4</td>
<td></td>
<td>(0.4289, 0.0000)</td>
<td></td>
</tr>
</tbody>
</table>