

# NAG Library Function Document

## nag\_fresnel\_c\_vector (s20arc)

### 1 Purpose

nag\_fresnel\_c\_vector (s20arc) returns an array of values for the Fresnel integral  $C(x)$ .

### 2 Specification

```
#include <nag.h>
#include <nags.h>
void nag_fresnel_c_vector (Integer n, const double x[], double f[],
                          NagError *fail)
```

### 3 Description

nag\_fresnel\_c\_vector (s20arc) evaluates an approximation to the Fresnel integral

$$C(x_i) = \int_0^{x_i} \cos\left(\frac{\pi}{2}t^2\right) dt$$

for an array of arguments  $x_i$ , for  $i = 1, 2, \dots, n$ .

**Note:**  $C(x) = -C(-x)$ , so the approximation need only consider  $x \geq 0.0$ .

The function is based on three Chebyshev expansions:

For  $0 < x \leq 3$ ,

$$C(x) = x \sum_{r=0} a_r T_r(t), \quad \text{with } t = 2\left(\frac{x}{3}\right)^4 - 1.$$

For  $x > 3$ ,

$$C(x) = \frac{1}{2} + \frac{f(x)}{x} \sin\left(\frac{\pi}{2}x^2\right) - \frac{g(x)}{x^3} \cos\left(\frac{\pi}{2}x^2\right),$$

where  $f(x) = \sum_{r=0} b_r T_r(t)$ ,

and  $g(x) = \sum_{r=0} c_r T_r(t)$ ,

with  $t = 2\left(\frac{3}{x}\right)^4 - 1$ .

For small  $x$ ,  $C(x) \simeq x$ . This approximation is used when  $x$  is sufficiently small for the result to be correct to **machine precision**.

For large  $x$ ,  $f(x) \simeq \frac{1}{\pi}$  and  $g(x) \simeq \frac{1}{\pi^2}$ . Therefore for moderately large  $x$ , when  $\frac{1}{\pi^2 x^3}$  is negligible compared with  $\frac{1}{2}$ , the second term in the approximation for  $x > 3$  may be dropped. For very large  $x$ , when  $\frac{1}{\pi x}$  becomes negligible,  $C(x) \simeq \frac{1}{2}$ . However there will be considerable difficulties in calculating  $\sin\left(\frac{\pi}{2}x^2\right)$  accurately before this final limiting value can be used. Since  $\sin\left(\frac{\pi}{2}x^2\right)$  is periodic, its value is essentially determined by the fractional part of  $x^2$ . If  $x^2 = N + \theta$ , where  $N$  is an integer and  $0 \leq \theta < 1$ , then  $\sin\left(\frac{\pi}{2}x^2\right)$  depends on  $\theta$  and on  $N$  modulo 4. By exploiting this fact, it is possible to retain some

significance in the calculation of  $\sin\left(\frac{\pi}{2}x^2\right)$  either all the way to the very large  $x$  limit, or at least until the integer part of  $\frac{x}{2}$  is equal to the maximum integer allowed on the machine.

## 4 References

Abramowitz M and Stegun I A (1972) *Handbook of Mathematical Functions* (3rd Edition) Dover Publications

## 5 Arguments

- |    |   |                     |
|----|---|---------------------|
| 1: | <b>n</b> – Integer  | <i>Input</i>        |
|    | <i>On entry:</i> $n$ , the number of points.                                    |                     |
|    | <i>Constraint:</i> $n \geq 0$ .   |                     |
| 2: | <b>x[n]</b> – const double  | <i>Input</i>        |
|    | <i>On entry:</i> the argument $x_i$ of the function, for $i = 1, 2, \dots, n$ . |                     |
| 3: | <b>f[n]</b> – double  | <i>Output</i>       |
|    | <i>On exit:</i> $C(x_i)$ , the function values.                                 |                     |
| 4: | <b>fail</b> – NagError *  | <i>Input/Output</i> |
|    | The NAG error argument (see Section 3.6 in the Essential Introduction).         |                     |

## 6 Error Indicators and Warnings

### NE\_BAD\_PARAM

On entry, argument  $\langle value \rangle$  had an illegal value.

### NE\_INT

On entry, **n** =  $\langle value \rangle$ .  
Constraint:  $n \geq 0$ .

### NE\_INTERNAL\_ERROR

An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please contact NAG for assistance.

## 7 Accuracy

Let  $\delta$  and  $\epsilon$  be the relative errors in the argument and result respectively.

If  $\delta$  is somewhat larger than the *machine precision* (i.e if  $\delta$  is due to data errors etc.), then  $\epsilon$  and  $\delta$  are approximately related by:

$$\epsilon \simeq \left| \frac{x \cos\left(\frac{\pi}{2}x^2\right)}{C(x)} \right| \delta.$$

Figure 1 shows the behaviour of the error amplification factor  $\left| \frac{x \cos\left(\frac{\pi}{2}x^2\right)}{C(x)} \right|$ .

However, if  $\delta$  is of the same order as the *machine precision*, then rounding errors could make  $\epsilon$  slightly larger than the above relation predicts.

For small  $x$ ,  $\epsilon \simeq \delta$  and there is no amplification of relative error.

For moderately large values of  $x$ ,

$$\epsilon \simeq \left| 2x \cos\left(\frac{\pi}{2}x^2\right) \right| \delta$$

and the result will be subject to increasingly large amplification of errors. However the above relation breaks down for large values of  $x$  (i.e., when  $\frac{1}{x^2}$  is of the order of the *machine precision*); in this region the relative error in the result is essentially bounded by  $\frac{2}{\pi x}$ .

Hence the effects of error amplification are limited and at worst the relative error loss should not exceed half the possible number of significant figures.

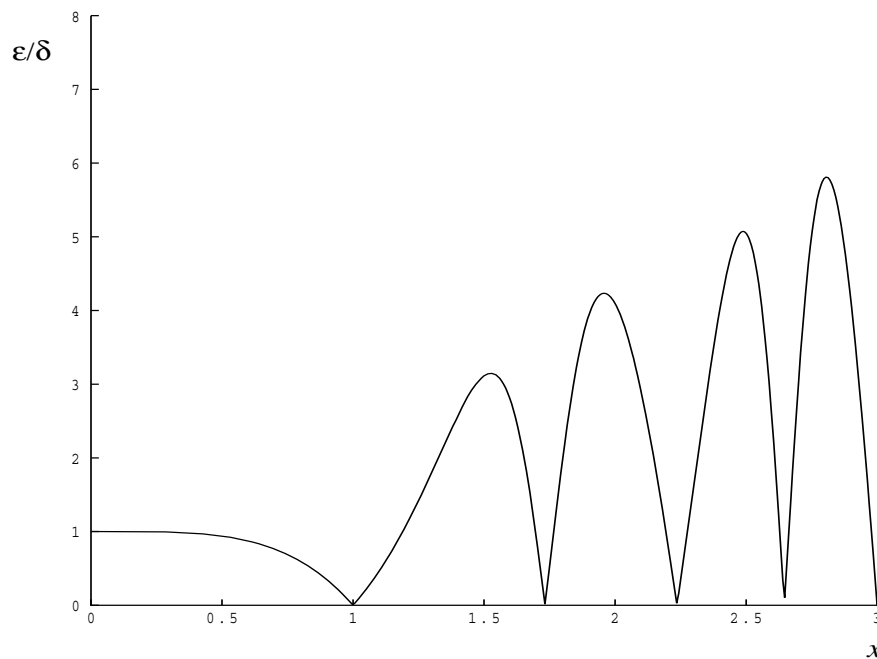


Figure 1

## 8 Parallelism and Performance

Not applicable.

## 9 Further Comments

None.

## 10 Example

This example reads values of  $x$  from a file, evaluates the function at each value of  $x_i$  and prints the results.

## 10.1 Program Text

```

/* nag_fresnel_c_vector (s20arc) Example Program.
 *
 * Copyright 2011, Numerical Algorithms Group.
 *
 * Mark 23 2011.
 */
#include <nag.h>
#include <stdio.h>
#include <nag_stdlib.h>
#include <nags.h>

int main(void)
{
    Integer    exit_status = 0;
    Integer    i, n;
    double     *f = 0, *x = 0;
    NagError   fail;

    INIT_FAIL(fail);

    /* Skip heading in data file */
    scanf("%*[^\\n]");

    printf("nag_fresnel_c_vector (s20arc) Example Program Results\\n");
    printf("\\n");
    printf("      x          f\\n");
    printf("\\n");
    scanf("%ld", &n);
    scanf("%*[^\\n]");

    /* Allocate memory */
    if (!(x = NAG_ALLOC(n, double)) ||
        !(f = NAG_ALLOC(n, double)))
    {
        printf("Allocation failure\\n");
        exit_status = -1;
        goto END;
    }

    for (i=0; i<n; i++)
        scanf("%lf", &x[i]);
    scanf("%*[^\\n]");

    /* nag_fresnel_c_vector (s20arc).
     * Fresnel Integral C(x)
     */
    nag_fresnel_c_vector(n, x, f, &fail);
    if (fail.code!=NE_NOERROR)
    {
        printf("Error from nag_fresnel_c_vector (s20arc).\\n%s\\n",
              fail.message);
        exit_status = 1;
        goto END;
    }

    for (i=0; i<n; i++)
        printf(" %11.3e %11.3e\\n", x[i], f[i]);

    END:
    NAG_FREE(f);
    NAG_FREE(x);

    return exit_status;
}

```

## 10.2 Program Data

nag\_fresnel\_c\_vector (s20arc) Example Program Data

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0.0 0.5 1.0 2.0 4.0 5.0 6.0 8.0 10.0 -1.0 1000.0

## 10.3 Program Results

nag\_fresnel\_c\_vector (s20arc) Example Program Results

x	f
0.000e+00	0.000e+00
5.000e-01	4.923e-01
1.000e+00	7.799e-01
2.000e+00	4.883e-01
4.000e+00	4.984e-01
5.000e+00	5.636e-01
6.000e+00	4.995e-01
8.000e+00	4.998e-01
1.000e+01	4.999e-01
-1.000e+00	-7.799e-01
1.000e+03	5.000e-01

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