

NAG Library Function Document

nag_ztrtrs (f07tsc)

1 Purpose

nag_ztrtrs (f07tsc) solves a complex triangular system of linear equations with multiple right-hand sides, $AX = B$, $A^T X = B$ or $A^H X = B$.

2 Specification

```
#include <nag.h>
#include <nagf07.h>

void nag_ztrtrs (Nag_OrderType order, Nag_UploType uplo,
                Nag_TransType trans, Nag_DiagType diag, Integer n, Integer nrhs,
                const Complex a[], Integer pda, Complex b[], Integer pdb,
                NagError *fail)
```

3 Description

nag_ztrtrs (f07tsc) solves a complex triangular system of linear equations $AX = B$, $A^T X = B$ or $A^H X = B$.

4 References

Golub G H and Van Loan C F (1996) *Matrix Computations* (3rd Edition) Johns Hopkins University Press, Baltimore

Higham N J (1989) The accuracy of solutions to triangular systems *SIAM J. Numer. Anal.* **26** 1252–1265

5 Arguments

1: **order** – Nag_OrderType *Input*

On entry: the **order** argument specifies the two-dimensional storage scheme being used, i.e., row-major ordering or column-major ordering. C language defined storage is specified by **order** = Nag_RowMajor. See Section 3.2.1.3 in the Essential Introduction for a more detailed explanation of the use of this argument.

Constraint: **order** = Nag_RowMajor or Nag_ColMajor.

2: **uplo** – Nag_UploType *Input*

On entry: specifies whether A is upper or lower triangular.

uplo = Nag_Upper
 A is upper triangular.

uplo = Nag_Lower
 A is lower triangular.

Constraint: **uplo** = Nag_Upper or Nag_Lower.

3: **trans** – Nag_TransType *Input*

On entry: indicates the form of the equations.

trans = Nag_NoTrans
The equations are of the form $AX = B$.

- trans** = Nag_Trans
The equations are of the form $A^T X = B$.
- trans** = Nag_ConjTrans
The equations are of the form $A^H X = B$.
- Constraint:* **trans** = Nag_NoTrans, Nag_Trans or Nag_ConjTrans.
- 4: **diag** – Nag_DiagType *Input*
On entry: indicates whether A is a nonunit or unit triangular matrix.
- diag** = Nag_NonUnitDiag
 A is a nonunit triangular matrix.
- diag** = Nag_UnitDiag
 A is a unit triangular matrix; the diagonal elements are not referenced and are assumed to be 1.
- Constraint:* **diag** = Nag_NonUnitDiag or Nag_UnitDiag.
- 5: **n** – Integer *Input*
On entry: n , the order of the matrix A .
Constraint: $n \geq 0$.
- 6: **nrhs** – Integer *Input*
On entry: r , the number of right-hand sides.
Constraint: **nrhs** ≥ 0 .
- 7: **a**[*dim*] – const Complex *Input*
Note: the dimension, *dim*, of the array **a** must be at least $\max(1, \mathbf{pda} \times \mathbf{n})$.
On entry: the n by n triangular matrix A .
If **order** = 'Nag_ColMajor', A_{ij} is stored in **a**[($j - 1$) \times **pda** + $i - 1$].
If **order** = 'Nag_RowMajor', A_{ij} is stored in **a**[($i - 1$) \times **pda** + $j - 1$].
If **uplo** = 'Nag_Upper', the upper triangular part of A must be stored and the elements of the array below the diagonal are not referenced.
If **uplo** = 'Nag_Lower', the lower triangular part of A must be stored and the elements of the array above the diagonal are not referenced.
If **diag** = 'Nag_UnitDiag', the diagonal elements of A are assumed to be 1, and are not referenced.
- 8: **pda** – Integer *Input*
On entry: the stride separating row or column elements (depending on the value of **order**) of the matrix A in the array **a**.
Constraint: **pda** $\geq \max(1, \mathbf{n})$.
- 9: **b**[*dim*] – Complex *Input/Output*
Note: the dimension, *dim*, of the array **b** must be at least
 $\max(1, \mathbf{pdb} \times \mathbf{nrhs})$ when **order** = Nag_ColMajor;
 $\max(1, \mathbf{n} \times \mathbf{pdb})$ when **order** = Nag_RowMajor.
The (i, j)th element of the matrix B is stored in
b[($j - 1$) \times **pdb** + $i - 1$] when **order** = Nag_ColMajor;
b[($i - 1$) \times **pdb** + $j - 1$] when **order** = Nag_RowMajor.

On entry: the n by r right-hand side matrix B .

On exit: the n by r solution matrix X .

10: **pdb** – Integer

Input

On entry: the stride separating row or column elements (depending on the value of **order**) in the array **b**.

Constraints:

if **order** = Nag_ColMajor, **pdb** \geq $\max(1, \mathbf{n})$;
if **order** = Nag_RowMajor, **pdb** \geq $\max(1, \mathbf{nrhs})$.

11: **fail** – NagError *

Input/Output

The NAG error argument (see Section 3.6 in the Essential Introduction).

6 Error Indicators and Warnings

NE_ALLOC_FAIL

Dynamic memory allocation failed.

NE_BAD_PARAM

On entry, argument $\langle value \rangle$ had an illegal value.

NE_INT

On entry, **n** = $\langle value \rangle$.

Constraint: **n** \geq 0.

On entry, **nrhs** = $\langle value \rangle$.

Constraint: **nrhs** \geq 0.

On entry, **pda** = $\langle value \rangle$.

Constraint: **pda** $>$ 0.

On entry, **pdb** = $\langle value \rangle$.

Constraint: **pdb** $>$ 0.

NE_INT_2

On entry, **pda** = $\langle value \rangle$ and **n** = $\langle value \rangle$.

Constraint: **pda** \geq $\max(1, \mathbf{n})$.

On entry, **pdb** = $\langle value \rangle$ and **n** = $\langle value \rangle$.

Constraint: **pdb** \geq $\max(1, \mathbf{n})$.

On entry, **pdb** = $\langle value \rangle$ and **nrhs** = $\langle value \rangle$.

Constraint: **pdb** \geq $\max(1, \mathbf{nrhs})$.

NE_INTERNAL_ERROR

An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please contact NAG for assistance.

NE_SINGULAR

$a(\langle value \rangle, \langle value \rangle)$ is exactly zero. A is singular and the solution has not been computed.

7 Accuracy

The solutions of triangular systems of equations are usually computed to high accuracy. See Higham (1989).

For each right-hand side vector b , the computed solution x is the exact solution of a perturbed system of equations $(A + E)x = b$, where

$$|E| \leq c(n)\epsilon|A|,$$

$c(n)$ is a modest linear function of n , and ϵ is the *machine precision*.

If \hat{x} is the true solution, then the computed solution x satisfies a forward error bound of the form

$$\frac{\|x - \hat{x}\|_\infty}{\|x\|_\infty} \leq c(n) \text{cond}(A, x)\epsilon, \quad \text{provided} \quad c(n) \text{cond}(A, x)\epsilon < 1,$$

where $\text{cond}(A, x) = \| |A^{-1}| |A| |x| \|_\infty / \|x\|_\infty$.

Note that $\text{cond}(A, x) \leq \text{cond}(A) = \| |A^{-1}| |A| \|_\infty \leq \kappa_\infty(A)$; $\text{cond}(A, x)$ can be much smaller than $\text{cond}(A)$ and it is also possible for $\text{cond}(A^H)$, which is the same as $\text{cond}(A^T)$, to be much larger (or smaller) than $\text{cond}(A)$.

Forward and backward error bounds can be computed by calling `nag_ztrrfs` (f07tvc), and an estimate for $\kappa_\infty(A)$ can be obtained by calling `nag_ztrcon` (f07tuc) with `norm = Nag_InfNorm`.

8 Parallelism and Performance

`nag_ztrtrs` (f07tsc) is not threaded by NAG in any implementation.

`nag_ztrtrs` (f07tsc) makes calls to BLAS and/or LAPACK routines, which may be threaded within the vendor library used by this implementation. Consult the documentation for the vendor library for further information.

Please consult the Users' Note for your implementation for any additional implementation-specific information.

9 Further Comments

The total number of real floating-point operations is approximately $4n^2r$.

The real analogue of this function is `nag_dtrtrs` (f07tec).

10 Example

This example solves the system of equations $AX = B$, where

$$A = \begin{pmatrix} 4.78 + 4.56i & 0.00 + 0.00i & 0.00 + 0.00i & 0.00 + 0.00i \\ 2.00 - 0.30i & -4.11 + 1.25i & 0.00 + 0.00i & 0.00 + 0.00i \\ 2.89 - 1.34i & 2.36 - 4.25i & 4.15 + 0.80i & 0.00 + 0.00i \\ -1.89 + 1.15i & 0.04 - 3.69i & -0.02 + 0.46i & 0.33 - 0.26i \end{pmatrix}$$

and

$$B = \begin{pmatrix} -14.78 - 32.36i & -18.02 + 28.46i \\ 2.98 - 2.14i & 14.22 + 15.42i \\ -20.96 + 17.06i & 5.62 + 35.89i \\ 9.54 + 9.91i & -16.46 - 1.73i \end{pmatrix}.$$

10.1 Program Text

```

/* nag_ztrtrs (f07tsc) Example Program.
 *
 * Copyright 2001 Numerical Algorithms Group.
 *
 * Mark 7, 2001.
 */

#include <stdio.h>
#include <nag.h>
#include <nag_stdlib.h>
#include <nagf07.h>
#include <nagx04.h>

int main(void)
{
    /* Scalars */
    Integer      i, j, n, nrhs, pda, pdb;
    Integer      exit_status = 0;
    Nag_UploType uplo;
    NagError     fail;
    Nag_OrderType order;
    /* Arrays */
    char         nag_enum_arg[40];
    Complex      *a = 0, *b = 0;

#ifdef NAG_COLUMN_MAJOR
#define A(I, J) a[(J-1)*pda + I - 1]
#define B(I, J) b[(J-1)*pdb + I - 1]
    order = Nag_ColMajor;
#else
#define A(I, J) a[(I-1)*pda + J - 1]
#define B(I, J) b[(I-1)*pdb + J - 1]
    order = Nag_RowMajor;
#endif

    INIT_FAIL(fail);

    printf("nag_ztrtrs (f07tsc) Example Program Results\n\n");

    /* Skip heading in data file */
    scanf("%*[\n] ");
    scanf("%ld%ld%*[\n] ", &n, &nrhs);
#ifdef NAG_COLUMN_MAJOR
    pda = n;
    pdb = n;
#else
    pda = n;
    pdb = nrhs;
#endif

    /* Allocate memory */
    if (!(a = NAG_ALLOC(n * n, Complex)) ||
        !(b = NAG_ALLOC(n * nrhs, Complex)))
    {
        printf("Allocation failure\n");
        exit_status = -1;
        goto END;
    }

    /* Read A and B from data file */
    scanf(" %39s%*[\n] ", nag_enum_arg);
    /* nag_enum_name_to_value (x04nac).
     * Converts NAG enum member name to value
     */
    uplo = (Nag_UploType) nag_enum_name_to_value(nag_enum_arg);

    if (uplo == Nag_Upper)
    {

```

```

    for (i = 1; i <= n; ++i)
    {
        for (j = i; j <= n; ++j)
            scanf(" ( %lf , %lf )", &A(i, j).re, &A(i, j).im);
    }
    scanf("%*[\n] ");
}
else
{
    for (i = 1; i <= n; ++i)
    {
        for (j = 1; j <= i; ++j)
            scanf(" ( %lf , %lf )", &A(i, j).re, &A(i, j).im);
    }
    scanf("%*[\n] ");
}
for (i = 1; i <= n; ++i)
{
    for (j = 1; j <= nrhs; ++j)
        scanf(" ( %lf , %lf )", &B(i, j).re, &B(i, j).im);
}
scanf("%*[\n] ");

/* Compute solution */
/* nag_ztrtrs (f07tsc).
 * Solution of complex triangular system of linear
 * equations, multiple right-hand sides
 */
nag_ztrtrs(order, uplo, Nag_NoTrans, Nag_NonUnitDiag, n,
           nrhs, a, pda, b, pdb, &fail);
if (fail.code != NE_NOERROR)
{
    printf("Error from nag_ztrtrs (f07tsc).\n%s\n", fail.message);
    exit_status = 1;
    goto END;
}

/* Print solution */
/* nag_gen_complx_mat_print_comp (x04dbc).
 * Print complex general matrix (comprehensive)
 */
fflush(stdout);
nag_gen_complx_mat_print_comp(order, Nag_GeneralMatrix, Nag_NonUnitDiag, n,
                              nrhs, b, pdb, Nag_BracketForm, "%7.4f",
                              "Solution(s)", Nag_IntegerLabels, 0,
                              Nag_IntegerLabels, 0, 80, 0, 0, &fail);
if (fail.code != NE_NOERROR)
{
    printf("Error from nag_gen_complx_mat_print_comp (x04dbc).\n%s\n",
          fail.message);
    exit_status = 1;
    goto END;
}

END:
NAG_FREE(a);
NAG_FREE(b);

return exit_status;
}

```

10.2 Program Data

```
nag_ztrtrs (f07tsc) Example Program Data
  4  2                                     :Values of n and nrhs
  Nag_Lower                               :Value of uplo
  ( 4.78, 4.56)
  ( 2.00,-0.30) (-4.11, 1.25)
  ( 2.89,-1.34) ( 2.36,-4.25) ( 4.15, 0.80)
  (-1.89, 1.15) ( 0.04,-3.69) (-0.02, 0.46) ( 0.33,-0.26) :End of matrix A
  (-14.78,-32.36) (-18.02, 28.46)
  ( 2.98, -2.14) ( 14.22, 15.42)
  (-20.96, 17.06) ( 5.62, 35.89)
  ( 9.54, 9.91) (-16.46, -1.73)                                     :End of matrix B
```

10.3 Program Results

```
nag_ztrtrs (f07tsc) Example Program Results
```

```
Solution(s)
           1           2
1  (-5.0000,-2.0000) ( 1.0000, 5.0000)
2  (-3.0000,-1.0000) (-2.0000,-2.0000)
3  ( 2.0000, 1.0000) ( 3.0000, 4.0000)
4  ( 4.0000, 3.0000) ( 4.0000,-3.0000)
```
