

## NAG Library Function Document

### nag\_hermitian\_lin\_eqn\_mult\_rhs (f04awc)

#### 1 Purpose

nag\_hermitian\_lin\_eqn\_mult\_rhs (f04awc) calculates the approximate solution of a set of complex Hermitian positive definite linear equations with multiple right-hand sides,  $AX = B$ , where  $A$  has been factorized by nag\_complex\_cholesky (f01bnc).

#### 2 Specification

```
#include <nag.h>
#include <nagf04.h>

void nag_hermitian_lin_eqn_mult_rhs (Integer n, Integer nrhs, Complex a[],
    Integer tda, double p[], const Complex b[], Integer tdb, Complex x[],
    Integer tdx, NagError *fail)
```

#### 3 Description

To solve a set of complex linear equations,  $AX = B$ , where  $A$  is positive definite Hermitian, this function must be preceded by a call to nag\_complex\_cholesky (f01bnc) which computes a Cholesky factorization  $A = U^H U$ , where  $U$  is an upper triangular matrix with real diagonal elements. The columns  $x$  of the solution  $X$  are found in two steps  $U^H y = b$  and  $Ux = y$ , where  $b$  is a column of the right-hand side matrix  $B$ .

#### 4 References

Wilkinson J H and Reinsch C (1971) *Handbook for Automatic Computation II, Linear Algebra* Springer-Verlag

#### 5 Arguments

- 1: **n** – Integer *Input*  
*On entry:*  $n$ , the order of the matrix  $A$ .  
*Constraint:*  $n \geq 1$ .
- 2: **nrhs** – Integer *Input*  
*On entry:*  $r$ , the number of right-hand sides.  
*Constraint:*  $nrhs \geq 1$ .
- 3: **a[n × tda]** – Complex *Input*  
**Note:** the  $(i, j)$ th element of the matrix  $A$  is stored in  $\mathbf{a}[(i - 1) \times \mathbf{tda} + j - 1]$ .  
*On entry:* the off-diagonal elements of the upper triangular matrix  $U$  as returned by nag\_complex\_cholesky (f01bnc). The lower triangle of the array is not used.
- 4: **tda** – Integer *Input*  
*On entry:* the stride separating matrix column elements in the array  $\mathbf{a}$ .  
*Constraint:*  $\mathbf{tda} \geq n$ .

- 5: **p[n]** – double *Input*  
*On entry:* the reciprocals of the diagonal elements of  $U$ , as returned by nag\_complex\_cholesky (f01bnc).
- 6: **b[n × tdb]** – const Complex *Input*  
**Note:** the  $(i, j)$ th element of the matrix  $B$  is stored in  $\mathbf{b}[(i - 1) \times \mathbf{tdb} + j - 1]$ .  
*On entry:* the  $n$  by  $r$  right-hand side matrix  $B$ . See also Section 9.
- 7: **tdb** – Integer *Input*  
*On entry:* the stride separating matrix column elements in the array  $\mathbf{b}$ .  
**Constraint:**  $\mathbf{tdb} \geq \mathbf{nrhs}$ .
- 8: **x[n × tdx]** – Complex *Output*  
**Note:** the  $(i, j)$ th element of the matrix  $X$  is stored in  $\mathbf{x}[(i - 1) \times \mathbf{tdx} + j - 1]$ .  
*On exit:* the  $n$  by  $r$  solution matrix  $X$ . See also Section 9.
- 9: **tdx** – Integer *Input*  
*On entry:* the stride separating matrix column elements in the array  $\mathbf{x}$ .  
**Constraint:**  $\mathbf{tdx} \geq \mathbf{nrhs}$ .
- 10: **fail** – NagError \* *Input/Output*  
The NAG error argument (see Section 3.6 in the Essential Introduction).

## 6 Error Indicators and Warnings

### NE\_2\_INT\_ARG\_LT

On entry,  $\mathbf{tda} = \langle \text{value} \rangle$  while  $\mathbf{n} = \langle \text{value} \rangle$ . These arguments must satisfy  $\mathbf{tda} \geq \mathbf{n}$ .

On entry,  $\mathbf{tdb} = \langle \text{value} \rangle$  while  $\mathbf{nrhs} = \langle \text{value} \rangle$ . These arguments must satisfy  $\mathbf{tdb} \geq \mathbf{nrhs}$ .

On entry,  $\mathbf{tdx} = \langle \text{value} \rangle$  while  $\mathbf{nrhs} = \langle \text{value} \rangle$ . These arguments must satisfy  $\mathbf{tdx} \geq \mathbf{nrhs}$ .

### NE\_INT\_ARG\_LT

On entry,  $\mathbf{n} = \langle \text{value} \rangle$ .

Constraint:  $\mathbf{n} \geq 1$ .

On entry,  $\mathbf{nrhs} = \langle \text{value} \rangle$ .

Constraint:  $\mathbf{nrhs} \geq 1$ .

## 7 Accuracy

The solutions should be the best possible for the precision of computation having regard to the condition of  $A$ . The computed solution  $x$ , corresponding to the right-hand side  $b$ , satisfies the bound

$$\frac{\|x - A^{-1}b\|}{\|A^{-1}b\|} \leq c\epsilon k.$$

Here  $c$  is a modest function of  $n$ ,  $\epsilon$  is the *machine precision*, and  $k$  is the condition number defined by

$$k = \|A\| \|A^{-1}\|.$$

## 8 Parallelism and Performance

Not applicable.

## 9 Further Comments

The time taken by `nag_hermitian_lin_eqn_mult_rhs` (f04awc) is approximately proportional to  $n^2r$ .

The function may be called with the same actual array supplied for arguments **b** and **x**, in which case the solution vectors will overwrite the right-hand sides.

## 10 Example

To solve the set of linear equations  $AX = B$  where  $A$  is the positive definite Hermitian matrix:

$$\begin{pmatrix} 15 & 1-2i & 2 & -4+3i \\ 1+2i & 20 & -2+i & 3-3i \\ 2 & -2-i & 18 & -1+2i \\ -4-3i & 3+3i & -1-2i & 26 \end{pmatrix}$$

and  $B$  is the single column vector:

$$\begin{pmatrix} 25+34i \\ 21+19i \\ 12-21i \\ 21-27i \end{pmatrix}.$$

### 10.1 Program Text

```

/* nag_hermitian_lin_eqn_mult_rhs (f04awc) Example Program.
 *
 * Copyright 1990 Numerical Algorithms Group.
 *
 * Mark 1, 1990.
 * Mark 8 revised, 2004.
 */

#include <nag.h>
#include <stdio.h>
#include <nag_stdlib.h>
#include <nagf01.h>
#include <nagf04.h>

#define COMPLEX(A) A.re, A.im
#define A(I, J) a[(I) *tda + J]
#define B(I, J) b[(I) *tdb + J]
#define X(I, J) x[(I) *tdx + J]
int main(void)
{
  Complex *a = 0, *b = 0, *x = 0;
  Integer exit_status = 0, i, j, n, nrhs, tda, tdb, tdx;
  NagError fail;
  double *p = 0;

  INIT_FAIL(fail);

  printf(
    "nag_hermitian_lin_eqn_mult_rhs (f04awc) Example Program Results\n");
  /* Skip heading in data file */
  scanf("%*[\n]");
  scanf("%ld", &n);
  nrhs = 1;
  if (n >= 1)
  {
    if (!(p = NAG_ALLOC(n, double)) ||
        !(a = NAG_ALLOC(n*n, Complex)) ||

```

```

        !(b = NAG_ALLOC(n*nrhs, Complex)) ||
        !(x = NAG_ALLOC(n*nrhs, Complex))
    {
        printf("Allocation failure\n");
        exit_status = -1;
        goto END;
    }
    tda = n;
    tdb = nrhs;
    tdx = nrhs;
}
else
{
    printf("Invalid n.\n");
    exit_status = 1;
    return exit_status;
}
for (i = 0; i < n; ++i)
    for (j = 0; j <= i; ++j)
        scanf(" ( %lf, %lf ) ", COMPLEX(&A(i, j)));
for (i = 0; i < n; ++i)
    for (j = 0; j < nrhs; ++j)
        scanf(" ( %lf, %lf ) ", COMPLEX(&B(i, j)));
/* Factorize A */
/* nag_complex_cholesky (f01bnc).
 * UU^H factorization of complex Hermitian positive-definite
 * matrix
 */
nag_complex_cholesky(n, a, tda, p, &fail);
if (fail.code != NE_NOERROR)
{
    printf("Error from nag_complex_cholesky (f01bnc).\n%s\n",
        fail.message);
    exit_status = 1;
    goto END;
}
/* Solve A */
/* nag_hermitian_lin_eqn_mult_rhs (f04awc).
 * Approximate solution of complex Hermitian
 * positive-definite simultaneous linear equations
 * (coefficient matrix already factorized by
 * nag_complex_cholesky (f01bnc))
 */
nag_hermitian_lin_eqn_mult_rhs(n, nrhs, a, tda, p, b, tdb, x, tdx, &fail);
if (fail.code != NE_NOERROR)
{
    printf(
        "Error from nag_hermitian_lin_eqn_mult_rhs (f04awc).\n%s\n",
        fail.message);
    exit_status = 1;
    goto END;
}
printf("\nSolution\n\n");
for (i = 0; i < n; ++i)
{
    for (j = 0; j < nrhs; ++j)
        printf(" (%7.4f,%7.4f)", COMPLEX(X(i, j)));
    printf("\n");
}
END:
NAG_FREE(p);
NAG_FREE(a);
NAG_FREE(b);
NAG_FREE(x);
return exit_status;
}

```

## 10.2 Program Data

```
nag_hermitian_lin_eqn_mult_rhs (f04awc) Example Program Data
4
(15.0, 0.0)
( 1.0, 2.0) (20.0, 0.0)
( 2.0, 0.0) (-2.0, -1.0) (18.0, 0.0)
(-4.0, -3.0) ( 3.0, 3.0) (-1.0, -2.0) (26.0, 0.0)
(25.0, 34.0) (21.0, 19.0) (12.0,-21.0) (21.0,-27.0)
```

## 10.3 Program Results

```
nag_hermitian_lin_eqn_mult_rhs (f04awc) Example Program Results
```

Solution

```
( 1.4917, 2.1788)
( 1.1629, 0.7698)
( 0.5506,-1.3977)
( 0.8691,-0.7655)
```

---