

Asset Prices in General Equilibrium with Transactions Costs and Recursive Utility

Adrian Buss¹, Raman Uppal,² Grigory Vilkov¹

¹Goethe University Frankfurt

²EDHEC Business School

January 26, 2011

NAG Quant Day in HoF, Frankfurt

Research Questions/ Objective

Study Asset Prices in an Economy with:

- Multiple agents
- Heterogeneous recursive (Epstein-Zin) preferences
- Heterogeneous beliefs
- Exchange economy
- Multiple assets (trees)
- Proportional transaction costs (to value and number of shares traded)
- Possibility of other frictions (shortsale, leverage constraints, etc)

Consequences of introducing TC for:

- Interest rate
- Stock price
- Expected return on the stock
- Volatility of stock and bond returns

Past Research/ Literature Review I

- General Equilibrium with TC
Vayanos 1998, Amihud and Mendelson 1986, Constantinides 1986, Heaton and Lucas 1996, Lo, Mamaysky, and Wang 2004, ...
- General Equilibrium with multiple agents and recursive utility
Dumas, Uppal and Wang 2000, ...
- Partial Equilibrium with TC
Davis and Norman 1990, Duffie and Sun 1990, Dumas and Luciano 1991, Muthuraman and Kumar 2006, ...
- Solution methods
Dumas and Lyasoff 2010, ...

Helicopter View

The Task and its Treatment

- Discrete time and space setup: recombining tree
- GE problems: backward-forward system of equations
- Use [Dumas and Lyasoff 2010](#) time shift: backward system
- Transaction costs: additional path-dependency
- Enhanced [numerical scheme](#) to deal with TC

Tools and NAG benefits

- Each Node of a tree/ state variables grid: system of equations
- Each system of equations: switching system depending on solver value
- Each system of equations: multivariate interpolation
- Use Matlab with NAG Toolbox: solver and interpolation
- Benefits compared to Matlab alone: $> 1,500\times$ speedup

Problem Formulation

Two agents, $l = 1, 2$ with utility function $u_{l,t}(c_{l,t,s})$, each solving:

$$\max_{c_{l,t,s}, \theta_{l,t,s}} u_{l,t}(c_{l,t,s}) + E_t \left[\sum_{\tau=1}^{T-t} u_{l,t+\tau}(c_{l,t+\tau}) \right]$$

subject to the floating budget constraint:

$$c_{l,t,s} + \theta_{l,t,s}^B B_{t,s} + \theta_{l,t,s}^S S_{l,t,s} + \tau(\theta_{l,t,s}^S, \theta_{l,t-1,s}^S, S_{l,t,s}, k) = \theta_{l,t-1,s-}^B B_{t,s} + \theta_{l,t-1,s-}^S (S_{l,t,s} + d_{t,s}),$$

where $\tau(\theta_{t,s}^S, \theta_{t-1,s}^S, S_{l,t,s}, k)$ — transaction costs function

++GE: market clearing conditions, kernel conditions

Optimality Conditions (FONC)

For each time t , each state (node) s , and each agent l , we have

$$\#1 \quad u'_{l,t} = \lambda_{l,t,s}$$

$$\#2 \quad E_t [u'_{l,t+1} B_{t+1,s+}] = \lambda_{l,t,s} B_{t,s}$$

$$\begin{aligned} \#3 \quad E_t \left[u'_{l,t+1} \left(S_{l,t+1,s+} + d_{t+1,s+} - \frac{\partial \tau}{\partial \theta_{l,t,s}^S} (\theta_{l,t+1,s+}^S, \theta_{l,t,s}^S, S_{l,t+1,s+}, k) \right) \right] \\ = \lambda_{l,t,s} \left(S_{l,t,s} + \frac{\partial \tau}{\partial \theta_{l,t,s}^S} (\theta_{l,t,s}^S, \theta_{l,t-1,s-}^S, S_{l,t,s}, k) \right) \end{aligned}$$

$$\begin{aligned} \#4 \quad c_{l,t,s} + \theta_{l,t,s}^B B_{t,s} + \theta_{l,t,s}^S S_{l,t,s} + \\ \tau(\theta_{l,t,s}^S, \theta_{l,t-1,s-}^S, S_{l,t,s}, k) = \theta_{l,t-1,s-}^B B_{t,s} + \theta_{l,t-1,s-}^S (S_{l,t,s} + d_{t,s}) \end{aligned}$$

Assuming proportional Transaction costs:

$$\frac{\partial \tau}{\partial \theta_{l,t,s}^S} (\theta_{l,t,s}^S, \theta_{l,t-1,s-}^S, S_{l,t,s}, k) = \frac{\partial \text{abs}(\theta_{l,t,s}^S - \theta_{l,t-1,s-}^S)}{\partial \theta_{l,t,s}^S} \cdot S_{l,t,s} \cdot k$$

Optimality Conditions: System of Equations

Proportional Transaction Costs → No-Trade and Trade Regions

For each value of the state variables on a grid, solve the following:

No-Trade Region (NTR) – no trading takes place

- Budget equations
- Market clearing conditions
- Supply equations

Trade Region (TR) – agents trade

- Budget equations
- Market clearing conditions
- Supply equations
- Kernel conditions

Traditional Numerical Scheme: Formulation (w/o TC)

State variables (grid over):

- (traditionally) entering wealth $\theta_{l,t-1,s-}^B B_{t,s} + \theta_{l,t-1,s-}^S (S_{l,t,s} + d_{t,s})$
- (if with TC path-dependency) past portfolio holdings $\theta_{l,t-1,s-}^S$

Algorithm

- Work backwards
- Solve for current consumption $c_{l,t,s}$ and portfolio holdings $\theta_{l,t,s}^{S,B}$
- For each grid value interpolate $u'_{l,t+1}(c_{l,t+1,s+})$, $S_{l,t+1,s+}$, $B_{l,t+1,s+}$
- Create interpolating function for the earlier step

Traditional Numerical Scheme: Problems

The system is backward-forward!

For c_t and θ_t one needs:

- Future marginal utility $u'_{l,t+1}(c_{l,t+1,s+})$
- Future asset prices $S_{l,t+1,s+}, B_{l,t+1,s+}$
- Past portfolio holdings $\theta_{l,t-1,s-}^{B,S}$

c_t and θ_t affects:

- Future wealth, and hence $u'_{l,t+1}(c_{l,t+1,s+}), S_{l,t+1,s+}, B_{l,t+1,s+}$

One needs the convergence of the solution via expectation step

- Takes time..
- No guarantee of a positive outcome...
- Interpolation of a marginal utility is quite unstable...

Adjusting the Numerical Scheme: Principle

Major change:

Shift all equations (except for kernel condition) one time period forward!

State variables (grid over):

- Current consumption $c_{l,t,s}$
- (if with TC path-dependency) split the solution into two steps:
 - ▶ $\frac{\partial \tau}{\partial \theta_{l,t,s}^S}(\theta_{l,t,s}^S, \theta_{l,t-1,s-}^S, S_{l,t,s}, k) = +1 / -1 \times S_t k$ to get NTR
 - ▶ Past portfolio holdings $\theta_{l,t-1,s-}^S$ inside NTR

Idea of the Solution

- Work backwards
- Split the solution at each time point into two steps
 - ▶ Solve for the NTR boundaries with 2-point grid = {Trade, No Trade}
 - ▶ Solve the system inside of the NTR with full asset holdings grid
- Create distinct interpolating functions for each case
- Change the system of equations depending on where you are today

Adjusting the Numerical Scheme: Principle

Algorithm

- Work backwards

Solve for the boundaries of the NTR

- Solve for future consumption $c_{l,t+1,s+}$ and current portfolio $\theta_{l,t,s}^{S,B}$
- For each grid value interpolate $S_{l,t+1,s+}$, $B_{l,t+1,s+}$, $\theta_{l,t+1,s+}^{S,B}$
- Create interpolating function for the earlier step

Solve inside of NTR

- Solve for future consumption $c_{l,t+1,s+}$ and current bond holdings $\theta_{l,t,s}^B$
- NTR \rightarrow stock holdings $\theta_{l,t,s}^S$ are carried forward from $t - 1$
- For each grid value interpolate $S_{l,t+1,s+}$, $B_{l,t+1,s+}$, $\theta_{l,t+1,s+}^{S,B}$
- Create interpolating function for the earlier step

Using NAG: Functions Used

Multidimensional Interpolation

One asset with TC

- **e01sg** – modified Shepard's method, two variables
- **e01sh** – evaluate interpolant computed by e01sg, two variables

Two assets with TC

- **e01sg** – modified Shepard's method, two variables
- **e01sh** – evaluate interpolant computed by e01sg, two variables
- **e01tg** – modified Shepard's method, three variables
- **e01th** – evaluate interpolant computed by e01tg, three variables

Solution of the System of Equations

- **c05nc** – system of nonlinear equations using function values only

Using NAG: Pros and Cons

Multidimensional Interpolation

NAG

- allows to save the interpolant in a structure, and use it later
- takes input table as vector, and can deal with non-square grids
- uses quadratic splines
- is limited by 3-dim interpolations
- has some “collinearity problems” when the step goes down

Matlab

- computes the interpolant on the fly
 - only takes matrices as inputs, hence grid limitations
 - uses cubic splines
 - can go to any dimension
- 50 – 100 times speed improvement by using NAG

Caution: Matlab may be more accurate due to higher dimension

Using NAG: Pros and Cons

Solution of the System of Equations

- NAG needs global variables: dangerous (e.g., parallel execution)
- Matlab can take parameters in the function
- NAG is 3 – 10 times faster