NAG Library Routine Document

F07JPF (ZPTSVX)

Note: before using this routine, please read the Users' Note for your implementation to check the interpretation of *bold italicised* terms and other implementation-dependent details.

1 Purpose

F07JPF (ZPTSVX) uses the factorization

 $A = LDL^{\mathrm{H}}$

to compute the solution to a complex system of linear equations

AX = B,

where A is an n by n Hermitian positive definite tridiagonal matrix and X and B are n by r matrices. Error bounds on the solution and a condition estimate are also provided.

2 Specification

```
SUBROUTINE F07JPF (FACT, N, NRHS, D, E, DF, EF, B, LDB, X, LDX, RCOND,
FERR, BERR, WORK, RWORK, INFO)
INTEGER N, NRHS, LDB, LDX, INFO
REAL (KIND=nag_wp) D(*), DF(*), RCOND, FERR(NRHS), BERR(NRHS), RWORK(N)
COMPLEX (KIND=nag_wp) E(*), EF(*), B(LDB,*), X(LDX,*), WORK(N)
CHARACTER(1) FACT
```

The routine may be called by its LAPACK name *zptsvx*.

3 Description

F07JPF (ZPTSVX) performs the following steps:

- 1. If FACT = 'N', the matrix A is factorized as $A = LDL^{H}$, where L is a unit lower bidiagonal matrix and D is diagonal. The factorization can also be regarded as having the form $A = U^{H}DU$.
- 2. If the leading *i* by *i* principal minor is not positive definite, then the routine returns with INFO = i. Otherwise, the factored form of *A* is used to estimate the condition number of the matrix *A*. If the reciprocal of the condition number is less than *machine precision*, INFO = N + 1 is returned as a warning, but the routine still goes on to solve for *X* and compute error bounds as described below.
- 3. The system of equations is solved for X using the factored form of A.
- 4. Iterative refinement is applied to improve the computed solution matrix and to calculate error bounds and backward error estimates for it.

4 References

Anderson E, Bai Z, Bischof C, Blackford S, Demmel J, Dongarra J J, Du Croz J J, Greenbaum A, Hammarling S, McKenney A and Sorensen D (1999) *LAPACK Users' Guide* (3rd Edition) SIAM, Philadelphia http://www.netlib.org/lapack/lug

Golub G H and Van Loan C F (1996) *Matrix Computations* (3rd Edition) Johns Hopkins University Press, Baltimore

Higham N J (2002) Accuracy and Stability of Numerical Algorithms (2nd Edition) SIAM, Philadelphia

5	Parameters
1:	FACT – CHARACTER(1) Input
	On entry: specifies whether or not the factorized form of the matrix A has been supplied.
	FACT = 'F' DF and EF contain the factorized form of the matrix A. DF and EF will not be modified.
	FACT = 'N' The matrix A will be copied to DF and EF and factorized.
	Constraint: $FACT = 'F'$ or 'N'.
2:	N – INTEGER Input
	On entry: n, the order of the matrix A. Constraint: $N \ge 0$.
3:	NRHS – INTEGER Input
	On entry: r, the number of right-hand sides, i.e., the number of columns of the matrix B. Constraint: NRHS ≥ 0 .
4:	D(*) – REAL (KIND=nag_wp) array Input
	Note: the dimension of the array D must be at least $max(1, N)$.
	On entry: the n diagonal elements of the tridiagonal matrix A .
5:	E(*) – COMPLEX (KIND=nag_wp) array Input
	Note: the dimension of the array E must be at least $max(1, N - 1)$.
	On entry: the $(n-1)$ subdiagonal elements of the tridiagonal matrix A.
6:	DF(*) – REAL (KIND=nag_wp) array Input/Output
	Note: the dimension of the array DF must be at least $max(1, N)$.
	On entry: if FACT = 'F', DF must contain the n diagonal elements of the diagonal matrix D from the LDL^{H} factorization of A.
	On exit: if $FACT = 'N'$, DF contains the <i>n</i> diagonal elements of the diagonal matrix <i>D</i> from the LDL^{H} factorization of <i>A</i> .
7:	EF(*) – COMPLEX (KIND=nag_wp) array Input/Output
	Note: the dimension of the array EF must be at least $max(1, N - 1)$.
	On entry: if FACT = 'F', EF must contain the $(n-1)$ subdiagonal elements of the unit bidiagonal factor L from the LDL^{H} factorization of A.
	On exit: if FACT = 'N', EF contains the $(n-1)$ subdiagonal elements of the unit bidiagonal factor L from the LDL^{H} factorization of A .
8:	B(LDB,*) – COMPLEX (KIND=nag_wp) array Input
	Note: the second dimension of the array B must be at least $max(1, NRHS)$.
	On entry: the n by r right-hand side matrix B .

9: LDB – INTEGER

On entry: the first dimension of the array B as declared in the (sub)program from which F07JPF (ZPTSVX) is called.

Constraint: LDB $\geq \max(1, N)$.

10: X(LDX,*) - COMPLEX (KIND=nag wp) array

Note: the second dimension of the array X must be at least max(1, NRHS).

On exit: if INFO = 0 or N + 1, the n by r solution matrix X.

11: LDX – INTEGER

On entry: the first dimension of the array X as declared in the (sub)program from which F07JPF (ZPTSVX) is called.

Constraint: $LDX \ge max(1, N)$.

12: RCOND – REAL (KIND=nag_wp)

On exit: the reciprocal condition number of the matrix A. If RCOND is less than the *machine* precision (in particular, if RCOND = 0.0), the matrix is singular to working precision. This condition is indicated by a return code of INFO = N + 1.

13: FERR(NRHS) – REAL (KIND=nag_wp) array

On exit: the forward error bound for each solution vector \hat{x}_j (the *j*th column of the solution matrix X). If x_j is the true solution corresponding to \hat{x}_j , FERR(*j*) is an estimated upper bound for the magnitude of the largest element in $(\hat{x}_j - x_j)$ divided by the magnitude of the largest element in \hat{x}_j .

14: BERR(NRHS) – REAL (KIND=nag wp) array

On exit: the component-wise relative backward error of each solution vector \hat{x}_j (i.e., the smallest relative change in any element of A or B that makes \hat{x}_j an exact solution).

15:	$WORK(N) - COMPLEX (KIND=nag_wp) array$	Workspace
16:	$RWORK(N) - REAL (KIND=nag_wp)$ array	Workspace

17: INFO – INTEGER

On exit: INFO = 0 unless the routine detects an error (see Section 6).

6 Error Indicators and Warnings

Errors or warnings detected by the routine:

INFO < 0

If INFO = -i, the *i*th argument had an illegal value. An explanatory message is output, and execution of the program is terminated.

INFO > 0 and $INFO \leq N$

If INFO = i and $i \le N$, the leading minor of order i of A is not positive definite, so the factorization could not be completed, and the solution has not been computed. RCOND = 0.0 is returned.

INFO = N + 1

The diagonal matrix D is nonsingular, but RCOND is less than *machine precision*, meaning that the matrix is singular to working precision. Nevertheless, the solution and error bounds are computed

Input

Input

Output

Output

Output

Output

Output

because there are a number of situations where the computed solution can be more accurate than the value of RCOND would suggest.

7 Accuracy

For each right-hand side vector b, the computed solution \hat{x} is the exact solution of a perturbed system of equations $(A + E)\hat{x} = b$, where

$$|E| \leq c(n)\epsilon |R^{\mathrm{T}}||R|$$
, where $R = D^{\frac{1}{2}}U$,

c(n) is a modest linear function of n, and ϵ is the *machine precision*. See Section 10.1 of Higham (2002) for further details.

If x is the true solution, then the computed solution \hat{x} satisfies a forward error bound of the form

$$\frac{\|x - \hat{x}\|_{\infty}}{\|\hat{x}\|_{\infty}} \le w_c \operatorname{cond}(A, \hat{x}, b)$$

where $\operatorname{cond}(A, \hat{x}, b) = \||A^{-1}|(|A||\hat{x}| + |b|)\|_{\infty}/\|\hat{x}\|_{\infty} \leq \operatorname{cond}(A) = \||A^{-1}||A|\|_{\infty} \leq \kappa_{\infty}(A)$. If \hat{x} is the *j*th column of X, then w_c is returned in BERR(*j*) and a bound on $\|x - \hat{x}\|_{\infty}/\|\hat{x}\|_{\infty}$ is returned in FERR(*j*). See Section 4.4 of Anderson *et al.* (1999) for further details.

8 Further Comments

The number of floating point operations required for the factorization, and for the estimation of the condition number of A is proportional to n. The number of floating point operations required for the solution of the equations, and for the estimation of the forward and backward error is proportional to nr, where r is the number of right-hand sides.

The condition estimation is based upon Equation (15.11) of Higham (2002). For further details of the error estimation, see Section 4.4 of Anderson *et al.* (1999).

The real analogue of this routine is F07JBF (DPTSVX).

9 Example

This example solves the equations

$$AX = B,$$

where A is the Hermitian positive definite tridiagonal matrix

$$A = \begin{pmatrix} 16.0 & 16.0 - 16.0i & 0 & 0\\ 16.0 + 16.0i & 41.0 & 18.0 + 9.0i & 0\\ 0 & 18.0 - 9.0i & 46.0 & 1.0 + 4.0i\\ 0 & 0 & 1.0 - 4.0i & 21.0 \end{pmatrix}$$

and

$$B = \begin{pmatrix} 64.0 + 16.0i & -16.0 - 32.0i \\ 93.0 + 62.0i & 61.0 - 66.0i \\ 78.0 - 80.0i & 71.0 - 74.0i \\ 14.0 - 27.0i & 35.0 + 15.0i \end{pmatrix}.$$

Error estimates for the solutions and an estimate of the reciprocal of the condition number of A are also output.

9.1 Program Text

Program f07jpfe

```
F07JPF Example Program Text
1
     Mark 24 Release. NAG Copyright 2012.
1
1
      .. Use Statements .
     Use nag_library, Only: nag_wp, x04dbf, zptsvx
1
      .. Implicit None Statement ..
     Implicit None
!
      .. Parameters ..
     Integer, Parameter
                                       :: nin = 5, nout = 6
      .. Local Scalars ..
1
     Real (Kind=nag_wp)
                                       :: rcond
                                       :: i, ifail, info, ldb, ldx, n, nrhs
     Integer
      .. Local Arrays ..
1
     Complex (Kind=nag_wp), Allocatable :: b(:,:), e(:), ef(:), work(:), x(:,:)
     Real (Kind=nag_wp), Allocatable :: berr(:), d(:), df(:), ferr(:),
                                                                                &
                                          rwork(:)
     Character (1)
                                        :: clabs(1), rlabs(1)
      .. Executable Statements ..
!
     Write (nout,*) 'FO7JPF Example Program Results'
     Write (nout,*)
     Flush (nout)
     Skip heading in data file
1
     Read (nin,*)
     Read (nin,*) n, nrhs
     ldb = n
      ldx = n
     Allocate (b(ldb,nrhs),e(n-1),ef(n-1),work(n),x(ldx,nrhs),berr(nrhs), &
       d(n),df(n),ferr(nrhs),rwork(n))
     Read the lower bidiagonal part of the tridiagonal matrix A and
1
     the right hand side b from data file
1
     Read (nin,*) d(1:n)
     Read (nin,*) e(1:n-1)
     Read (nin,*)(b(i,1:nrhs),i=1,n)
1
     Solve the equations AX = B for X
     The NAG name equivalent of zptsvx is f07jpf
1
     Call zptsvx('Not factored',n,nrhs,d,e,df,ef,b,ldb,x,ldx,rcond,ferr,berr, &
       work, rwork, info)
     If ((info==0) .Or. (info==n+1)) Then
1
       Print solution, error bounds and condition number
1
        ifail: behaviour on error exit
              =0 for hard exit, =1 for quiet-soft, =-1 for noisy-soft
1
       ifail = 0
       Call x04dbf('General',' ',n,nrhs,x,ldx,'Bracketed','F7.4', &
          'Solution(s)','Integer',rlabs,'Integer',clabs,80,0,ifail)
       Write (nout,*)
       Write (nout,*) 'Backward errors (machine-dependent)'
       Write (nout,99999) berr(1:nrhs)
       Write (nout,*)
       Write (nout,*) 'Estimated forward error bounds (machine-dependent)'
       Write (nout,99999) ferr(1:nrhs)
       Write (nout,*)
       Write (nout, *) 'Estimate of reciprocal condition number'
       Write (nout,99999) rcond
       If (info==n+1) Then
         Write (nout,*)
         Write (nout,*) 'The matrix A is singular to working precision'
       End If
     Else
```

9.2 Program Data

 F07JPF Example Program Data
 4
 2
 :Values of N and NRHS

 16.0
 41.0
 46.0
 21.0
 :End of diagonal D

 (16.0, 16.0)
 (18.0, -9.0)
 (1.0, -4.0)
 :End of sub-diagonal E

 (64.0, 16.0)
 (-16.0, -32.0)
 :End of sub-diagonal E

 (93.0, 62.0)
 (61.0, -66.0)
 :End of matrix B

9.3 **Program Results**

F07JPF Example Program Results